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A Simple Method for Testing Goodness of Fit in the Presence of Nuisance Parameters



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#### Summary.

This paper presents a method, based on the empirical distribution function, for testing goodness of fit (gf) under composite null hypotheses. After the unknown parameters are estimated from the entire data set, the procedure calls for the transformed sample to be randomly partitioned into a large number of groups, and a gf statistic calculated for each group. These statistics are used to construct a test which can attain, asymptotically, any desired level  $\alpha$ , and which requires for its implementation only standard tables of critical values. The procedure is particularly recommended when an a priori grouping of the sample can be employed and, hence, heterogeneous alternatives are quite plausible. It is shown that, under these alternatives, the power of the procedure compares favourably with that of other methods.

## 0. Introduction.

Historically, the primary concern of the classical theory of goodness-of-fit (gf) has been the testing of simple hypotheses. With the exception of chi-square tests, the problem of composite null hypotheses, until fairly recently, has received little analytical attention. Undoubtedly, a major obstacle is that the presence of nuisance parameters severely complicates the distribution theory, not only for statistics based on the sample distribution function but also for other gf methods. The implementation of Barton's [1956] extension to composite hypotheses of Neyman's [1937] "Smooth goodness-of-fit test", for example, requires extensive specialized tables. Similarly, the distribution of the Shapiro and Wilks [1965] statistic for testing normality has

proved intractable and their tables are based on Monte Carlo studies. Though, subsequently, a test for exponentiality was proposed (Shapiro and Wilk [1972]), these methods do not appear to be broadly applicable.

A more intuitive approach involves first estimating the unknown parameters, and then carrying out a probability integral transform of the observations employing the estimated distribution function. Durbin [1973] has shown that under regularity conditions, as the sample size tends to infinity, the resulting sequence of empirical processes converges weakly to a Gaussian process. This result provides a rigorous foundation for computing gf statistics for the estimated empirical process. Unfortunately, the distribution of the limit process depends on the underlying distribution of the observations, so that different tables are required for each particular application. An extensive survey of recent work in this area can be found in Neuhaus [1977].

To obviate the need for new tables, preparation of which requires considerable numerical work, various methods which permit the use of standard tables have been suggested. Durbin [1976] discusses two such techniques involving the use of randomization, and points out that their convenience may be outweighed by their undoubtedly poor power characteristics.

In this paper another randomization device is presented and its properties investigated. The procedure consists of firstly using the entire sample to estimate the nuisance parameters and, secondly, randomly dividing the data into a fairly large number of groups, no group ordinarily containing more than about 10 to 15 percent of the sample. Employing the (same) estimated distribution

function, each group of observations is mapped into [0,1] and for each, a gf statistic is computed. Given that there are m groups and a test of approximate level  $\alpha$  is desired, then each statistic should be composed with the upper  $\alpha/m$  percent point of the distribution appropriate to testing a simple hypothesis with the same number of observations as in the group. The null hypothesis is rejected if any of the m statistics exceed their critical values.

The intuitive justification for using the standard distribution is based on the assumption that no one group has a disproportionate influence on the value of the estimator. If ,indeed, that is the case, then from the standpoint of a single group, the parameter estimates appear to be superefficient (compare Darling [1955] p. 2-3). Hence, the effect of the estimation should become negligible as the total sample size tends to infinity, notwithstanding the fact that m such significance tests have been carried out. A rigorous presentation of the argument will be given in Section 1.

The above procedure has been motivated by a practical application (Braun [1977]) to data which consisted of closed birth interval lengths, hypothesized to have a gamma distribution involving unknown nuisance parameters. The adequacy of the model was of some interest, but no tables were available to carry out a proper test of fit. However, a natural grouping of the data by the parity of the interval led to the notion of separately testing each group of interval lengths of the same parity. The heuristics of the proposed procedure, outlined above, suggested the plausibility of using standard tables.

Although in this case the grouping was not done randomly, it seemed sufficient that the values of the parameter estimates played no role. In fact, it might be expected that the procedure would be most readily applied to those problems in which a natural a priori grouping is available, particularly if an alternative hypothesis of heterogeneity is being entertained. For example, in a test of normality carried out on data collected over several days, it might be suspected that one day's work differs from the others' and, thus, testing each day's data separately is intuitively attractive.

The power of the proposed procedure under such alternatives is studied in Section 2, where it is shown that, under certain conditions, the power approaches 1 as the sample size gets very large, while the power of the method carrying out a single significance test on the entire sample has power which is asymptotically only the level of the test. Heuristic arguments are subsequently advanced which suggest that the proposed procedure does well even for moderate sample sizes.

1. MAIN RESULT

## A. Asymptotic Validity

Let  $X_1, X_2, \ldots$  be iid with distribution function  $F(\cdot, \theta)$  where  $\theta$  is a vector of parameters that is partitioned as  $\theta = \begin{pmatrix} \theta \\ \theta \\ 2 \end{pmatrix}$ . Suppose the true (unknown) value of  $\theta$  is  $\theta_0 = \begin{pmatrix} \theta \\ \theta \\ 20 \end{pmatrix}$  and that the hypothesis to be tested is  $H_0: \theta_1 = \theta_{10}$ . Thus,  $\theta_2$  represents a vector of nuisance parameters.

For a given sample size N, let  $\hat{\theta}_{2N} = \hat{\theta}_{2N} (X_1, \dots, X_N)$  be an estimator of  $\theta_2$  and let  $\hat{\theta}_N = \begin{pmatrix} \theta & 10 \\ \theta & 2N \end{pmatrix}$ . Let  $\nu$  denote the closure of a

given neighbourhood of  $\theta_0$ . Following Durbin [1973], we make the following assumptions:

Assumption 1:

$$N^{\frac{1}{2}} (\hat{\theta}_{2N} - \theta_{20}) = N^{-\frac{1}{2}} \sum_{i=1}^{N} \ell(x_i, \theta_0) + \epsilon_N$$

where

(0)	$x_1, \ldots, x_N$ are iid observations from $F(\cdot, \theta)$ ,
(i)	$\ell$ is measurable and for a random observation x
	$E[\ell(\mathbf{x}, \theta_0)   \theta = \theta_0] = 0,$
(ii)	$E[\ell(x, \theta_0)\ell(x, \theta_0)'   \theta = \theta_0] = L(\theta_0)$ , a finite nonnegative -
	definite matrix,
(iii)	$\epsilon_{\rm N} \stackrel{\rm P}{\rightarrow} 0$ .

Assumption 2:

(i)  $F(x,\theta)$  is continuous in x for all  $\theta \in v$ .

(ii) Let  $x(t,\theta) = \inf \{x: F(x,\theta) = t\}$  be the inverse transformation of  $t = F(x,\theta)$ . Then the vector-valued function  $g(t,\theta_1,\theta_2)$  defined by

$$g(t,\theta_1,\theta_2) = \frac{\partial F(x,\theta)}{\partial \theta} \begin{vmatrix} x = x(t,\theta_1) \\ \theta = \theta_2 \end{vmatrix}$$

exists and is continuous in  $(t, \theta_1, \theta_2)$  for all  $\theta_1 \ge \theta_2 \ge v \ge v$  and all  $0 \le t \le 1$ .

<u>Remark:</u> Assumption 1 is slightly simpler than assumption Al (Durbin [1973], p.281) because we are not concerned here with a sequence of alternatives. Assumption 2 corrects a small error in Durbin's assumption A2. Once  $\hat{\theta}_{2N}$  has been calculated, the procedure calls for partitioning the sample into groups of possibly different sizes. For convenience of exposition, it is assumed in the sequel that the groups are of equal size n(N) so that the number of groups is m(N) = N/n(N). The dependence of n and m on N is usually suppressed in the notation. A gf statistic is then calculated for each group. For fixed  $\alpha \epsilon(0, \frac{1}{2})$ , let  $z_n(\alpha)$  denote the upper  $\alpha$  percent point of the standard distribution of the statistic for sample size n and let  $\alpha_m = 1 - (1 - \alpha)^{1/m}$ . The null hypothesis is rejected if and only if the largest of the calculated statistics exceeds  $Z_n(\alpha_m)$ .

<u>Theorem 1</u>: Suppose the procedure described above employs either a Kolmogorov-Smirnov (KS) statistic or the Cramer-von Mises (CM) statistic. Then under Assumptions 1 and 2, the level of the procedure  $\rightarrow \alpha$  as N  $\rightarrow \infty$ , provided that n(N) = 0 (N<sup>P</sup>) for some 0 \frac{1}{2}.

Theorem 1 is a direct consequence of the following two propositions which are established under its hypotheses ,following the introduction of some\_notation. Define

 $\hat{F}^{(i,N)}(t) = n^{-1} (\overset{\#}{\#} \text{ observations } x \text{ in group } i \text{ such that}$  $F(x, \hat{\theta}_N) \leq t)$ 

and

$$\hat{Y}^{(i,N)}(t) = n^{\frac{1}{2}}[\hat{F}^{(i,N)}(t) - t], \quad i = 1, 2, ..., m.$$

 $\hat{\mathtt{T}}^{(\texttt{i},\texttt{N})}$  denotes either one of the KS statistics:

$$\max\{0, \sup_{0 \leq t \leq 1} \hat{y}^{(i,N)}(t)\}, \max\{0, \sup_{0 \leq t \leq 1} - \hat{y}^{(i,N)}(t)\}, \sup_{0 \leq t \leq 1} |\hat{y}^{(i,N)}(t)|,$$

or the CM statistic:

$$\int_{0}^{1} \left[ \hat{y}^{(i,N)}(t) \right]^{2} dt.$$

The corresponding symbols without the carets are employed when  $\hat{\theta}_N$  is replaced by  $\theta_0$  .

Proposition 1: 
$$\max_{\substack{1 \leq i \leq m \\ \text{for some } q > 0}} T^{(i,N)} - T^{(i,N)} | < \gamma = o_p(N^{-q})$$

<u>Proof</u>: The proof depends on a basic relation derived in Durbin [1973]. Letting  $\hat{t}_N = \hat{t}_N(t) = F(x(t, \hat{\theta}_N), \theta_0)$ , we have

$$\hat{F}^{(i,N)}(t) = n^{-1}(^{\#} \text{ observations in group i such that} x \leq x(t, \hat{\theta}_N))$$

and

$$F^{(i,N)}(\hat{t}_{N}(t)) = n^{-1}(\# \text{ observations } x \text{ in group } i \text{ such}$$
  
that  $F(x,\theta_{0}) \leq \hat{t}_{N}(t)$ .

Thus,

$$\hat{F}^{(i,N)}(t) = F^{(i,N)}(\hat{t}_{N}(t)),$$
 (2.1)

Showing that  $\hat{F}^{(i,N)}(\cdot)$  and  $F^{(i,N)}(\cdot)$  are related by a random time transformation. The proof now differs slightly according to which class of statistics is considered.

(a) KS statistics. As a consequence of (2.1)

$$\hat{Y}^{(i,N)}(t) = n^{\frac{1}{2}} [\hat{F}^{(i,N)}(t) - t]$$

$$= n^{\frac{1}{2}} [F^{(i,N)}(\hat{t}_{N}) - \hat{t}_{N}] + n^{\frac{1}{2}} [\hat{t}_{N} - t]$$

$$= y^{(i,N)}(\hat{t}_{N}) + n^{\frac{1}{2}} [\hat{t}_{N} - t].$$

Since

$$\sup_{0 \leq t \leq 1} |y^{(i,N)}(\hat{t}_{N}(t))| = \sup_{0 \leq t \leq 1} |y^{(i,N)}(t)|$$

 $\hat{\mathbf{T}}^{(\texttt{i},\texttt{N})}$  and  $\mathbf{T}^{(\texttt{i},\texttt{N})}$  can differ by at most

$$\gamma_{\rm N} = n^{\frac{1}{2}} \delta_{\rm N} = n^{\frac{1}{2}} \sup_{\substack{0 \le t \le 1 \\ 0 \le t \le 1}} \hat{t}_{\rm N} (t) - t|.$$

The proof of Lemma 1 in Durbin [1973] shows that

$$\delta_{N} = \sup_{0 \le t \le 1} |\hat{t}_{N} - t| = o_{P}(N^{-r}), r < \frac{1}{2},$$

so that  $\gamma_N = O_P(N^{-q})$  some q > 0 as long as n = O(N).

(b) CM statistic. Again from (2.1),

$$\hat{\mathbf{T}}^{(\mathbf{i},\mathbf{N})} = \mathbf{n} \int_{0}^{1} [\hat{\mathbf{F}}^{(\mathbf{i},\mathbf{N})}(\mathbf{t}) - \mathbf{t}]^{2} d\mathbf{t}$$
$$= \mathbf{n} \int_{0}^{1} [\mathbf{F}^{(\mathbf{i},\mathbf{N})}(\hat{\mathbf{t}}_{\mathbf{N}}(\mathbf{t})) - \mathbf{t}]^{2} d\mathbf{t}$$

Suppose the observations in group i are denoted by  $x_1, \ldots, x_n$ . Then define

$$s_{j} = F(x_{j}, \theta_{0}) \qquad j = 1, \dots, n_{n}$$

and let  $t_1, \ldots, t_n$  be determined implicitly by the relations

$$s_j = \hat{t}_N(t_j)$$
  $j = 1, \dots, n$ .

Writing G(t) for  $F^{(i,N)}(\hat{t}_{N}(t))$ , it is clear that G(t) is the empirical df of the fictitious sample  $t_{1}, \ldots t_{n}$ , and  $\hat{T}^{(i,N)}$  is the corresponding CM statistic. On the other hand,  $T^{(i,N)}$  is the CM statistic of the sample  $s_{1}, \ldots, s_{n}$ . Now, using the formula

$$T^{(i,N)} = \sum_{j=1}^{n} (s_j - \frac{j-\frac{1}{2}}{n})^2 + 1/(12n),$$

together with the fact that

$$|t_{j} - s_{j}| < \delta_{N}$$
  $j = 1, ..., n,$ 

we obtain

$$|\hat{\mathbf{T}}^{(i,N)} - \mathbf{T}^{(i,N)}| < n\delta_{N} + \delta_{N}^{2} \equiv \gamma_{N}.$$

If  $n = o(N^P)$  some  $p < \frac{1}{2}$ , then  $\gamma_N = o_P(N^{-q})$  some  $q > 0. \Box$ 

Proposition 2:

$$|P\{\max \hat{T}^{(j,N)} \ge z_n(\alpha_m)\} - P\{\max T^{(j,N)} \ge z_n(\alpha_m)\}|$$
  
$$|z \le j \le m$$
  
$$\to 0 \text{ as } N \to \infty.$$

Proof: Since

$$\max_{\substack{\substack{i \leq j \leq m}}} | \widehat{T}^{(j,N)} - T^{(j,N)} | < \gamma_N,$$

it follows that

$$P\{\max_{\substack{1 \leq j \leq m \\ l \leq j \leq m }} T^{(j,N)} > z_{n}(\alpha_{m}) + \gamma_{N} \} < P\{\max_{\substack{1 \leq j \leq m \\ l \leq j \leq m }} T^{(j,N)} > z_{n}(\alpha_{m}) \}$$

$$< P\{\max_{\substack{1 \leq j \leq m \\ l \leq j \leq m }} T^{(j,N)} > z_{n}(\alpha_{m}) - \gamma_{N} \} (2.2)$$

The proof consists of showing that the change in the overall significance level caused by perturbing  $z_n(\alpha_m)$  by  $\gamma_N$  is asymptotically negligible as  $N \rightarrow \infty$ . This requires fairly precise knowledge of the functional relationship between critical values and their corresponding significance levels, particularly when both the sample size and the critical values tend to infinity.

For the sake of brevity, only the case of Smirnov's statistic  $\sqrt{n} \sup_{\substack{0 \leq t \leq 1}} y^{(i,N)}(t)$  will be considered. If  $\Phi_n^+$  (•) denotes the df of the statistic for sample size n, then Smirnov [1941] showed that

$$\rho_{n}(z) = 1 - \Phi_{n}^{+}(z) = e^{-2z^{2}} \{1 - \frac{2z}{3\sqrt{n}} + O(\frac{1}{n})\}$$
(2.3)  
as  $n \neq \infty$  for  $z = O(n^{1/6})$ .

Since  $z_n(\alpha_m) = O(\log N)$ , it is legitimate to use (2.3) to evaluate  $\rho_n(z_n(\alpha_m) + \gamma_N)$ . In fact,

$$\begin{split} \rho_{n}(z_{n}(\alpha_{m}) + \gamma_{N}) &= e^{-2z_{n}^{2}(\alpha_{m})} \left[ e^{-4z_{n}(\alpha_{m})\gamma_{N} - 2\gamma_{N}^{2}} \right] x \\ & \left[ 1 - \frac{2z_{n}(\alpha_{m}) - 2\gamma_{N}}{3\sqrt{n}} + O(\frac{1}{n}) \right] \\ &= \rho_{n}(z_{n}(\alpha_{m})) \left[ 1 + O_{P}(1/n) \right] \\ &= \alpha_{m} \left[ 1 + O_{P}(\frac{1}{n}) \right], \end{split}$$

with a similar result for  $\rho_n(z_n(\alpha_m) - \gamma_N)$ . Thus, the first and last expressions in (2.2) both tend to  $\alpha$  as  $N \rightarrow \infty$ .

An asymptotic expansion for the distribution of Kolmogorov's statistic can be found in Korolyuk [1955], while similar results for the CM statistic can be found in Anderson and Darling [1952] or Mogul'skii [1977].

## Practical Considerations

An important question in the application of this procedure is the choice of the group size(s) . As Proposition 1 makes clear, if the CM statistic is to be applied then the maximal group size n should be no more than  $N^{\frac{1}{2}}$ . In the case of KS statistics more latitude is permitted, but caution suggests that n be about .1N to .15N.

If the group structure is intrinsic to the problem, then another form of the question often arises. It may happen that some or all of the group sizes are rather small, say of the order of ten. In this situation, are the asymptotic results presented above relevant? The answer seems to be yes, provided that the total sample size is large and  $\hat{\theta}_{2N}$  is a good estimator of  $\theta_2$ .

When N is large, Proposition 1 shows that  $\gamma_N$  (which bounds  $|T^{(i,N)} - \hat{T}^{(i,N)}|$ ) tends to be small, particularly if n is small. Proposition 2 is more problematic since the proof requires n to tend to infinity, though at an admittedly slow rate. However, the work of Stephens [1970] provides some empirical evidence that even for small values of n, perturbing  $z_n(\alpha/m)$  by  $\gamma_N$  changes the corresponding critical value by a negligible amount.

Stephens has shown how the common gf statistics can be modified so that the critical values for  $n = \infty$  can be used for all sample sizes. For example, if  $D_n$  denotes Kolmogorov's statistic for sample size n, then Stephens suggests calculating

$$\widetilde{D} = D_n (n^{\frac{1}{2}} + .12 + .11n^{-\frac{1}{2}}),$$

and then treating  $\widetilde{D}$  as if it were distributed as  $\lim_{n \to \infty} \sqrt{n}D_n$ . Between the significance levels  $\alpha$  and the corresponding critical values z ( $\alpha$ ), the following relation holds:

$$\alpha = 2 \exp \left(-2z^{2}(\alpha)\right).$$

Furthermore, Stephens states that the approximation is quite good even for n very small, and that its accuracy increases as the

significance levels become more extreme. Such modifications of  $T^{(i,N)}$  and  $\hat{T}^{(i,N)}$  would differ by no more than  $O(\gamma_N)$ , and changing  $z(\alpha/m)$  by  $O(\gamma_N)$  has little effect on the corresponding significance level.

Because they both involve grouping, it would be of interest to compare the method suggested here with Durbin's half-sample method (Durbin [1976]).

The latter procedure carries out a single significance test on the N transformed observations, but the probability integral transform employs an estimate of  $\theta_2$  based on a randomly chosen half-sample. Durbin showed that as N  $\rightarrow \infty$ , the effect of the estimation on the distribution of the empirical process becomes negligible. The two methods use grouping in different phases: one when carrying out the significance testing, the other when constructing the estimator of the nuisance parameters.

Certainly these methods should be considered when the nonrandomized procedure cannot be implemented for lack of tables or because the distribution of the transformed observations depends on the values of the nuisance parameters. But choosing between them is difficult without supporting numerical evidence. However, the present method might be preferred when there is a natural grouping so that less arbitrariness is involved, or, when the testing problem is only a component of a larger study and the values of the nuisance parameters are of interest . In such cases the method which uses the final estimates (provided  $H_0$  is accepted) in carrying out the test might be easier to justify.

Finally when heterogeneous alternatives are a distinct possibility, the power of the method presumably can be enhanced by employing jackknife methods. That is, when the groups are balanced, the probability integral transform of the i<sup>th</sup> group uses  $\hat{\theta}_{2N}^{(i)}$  where  $\hat{\theta}_{2N}^{(i)}$  denotes the estimator of  $\theta_2$  constructed from all the observations except those in the i<sup>th</sup> group. If H<sub>0</sub> is accepted, the usual jackknife estimator of  $\theta_2$  based on the pseudo values constructed from  $\{\hat{\theta}_{2N}^{(i)}\}$  can be used for further investigations.

## 2. POWER

# A. <u>Preliminaries</u>

It is widely assumed that procedures involving extraneous randomization have poor power characteristics. Unfortunately, in the area of gf testing, very little seems to be known about the magnitude of the power loss even for different homogeneous alternatives. In the case of the present procedure, such calculations could be carried out exactly, if rather laboriously, using the formulas in Suzuki [1968]. This is postponed to a later investigation. For the moment, it must be assumed that the present method is generally not as powerful as the one based on the full (estimated) empirical process, and it's use can be recommended only when the latter's implementation is impractical or impossible. In any application, the set of P-values generated by the procedure can give only an indication of the adequacy of the fit.

As stated previously, the apparent arbitrariness of the procedure is diminished when a natural grouping of the data can

be employed. In such a case it is often quite plausible to fear "heterogeneous alternatives". This phrase refers to the situation in which the observations in a large majority of groups conform to the null hypothesis, while those in the remaining groups differ in one or more distributional characteristics. The k-sample slippage hypothesis is a classical parametric example. Since the present procedure tests each group separately, it should prove particularly sensitive to heterogeneous alternatives and some asymptotic results in this direction are presented in the following subsection. The remainder of the section develops heuristic arguments which suggest that against these alternatives, the power of the procedure compares favourably with that of other methods, even with only moderate sample sizes. At present, the discussion is limited to KS statistics only.

# B. Asymptotics

Let the sample consist of m groups each containing n independent observations for which the null hypothesis,  $H_0$ , specifies a common distribution  $F(\cdot,\theta)$  (cf. Section 1.A). Suppose that, in fact, only m- $\ell$  groups conform to  $H_0$ , while the remaining observations follow a different common distribution G. It will prove convenient to phrase the argument in terms of the procedures followed by three statisticians  $S_1, S_2$ , and  $S_3$ .

 $\underline{S}_1$  observes only the m- $\ell$  groups conforming to  $\underline{H}_0$  and his data (after transformation) is denoted by  $0 \leq \underline{t}_1 \leq \underline{t}_2 \leq \cdots \leq \underline{t}_{(m-\ell)n} \leq 1$ , while  $\underline{S}_2$  and  $\underline{S}_3$  both observe the entire sample; their observations (after transformation) are denoted by  $0 \leq \underline{v}_1 \leq \underline{v}_2 \leq \cdots \leq \underline{v}_{mn} \leq 1$ .  $\underline{S}_1$  and  $\underline{S}_2$  compute

$$\hat{d}_{1}^{+} = \max_{\substack{1 \leq j \leq (m-\ell) n}} \left[\frac{j}{(m-\ell)n} - t_{j}\right]$$

and

$$\hat{d}_2^{+} = \max_{\substack{1 \leq i \leq mn}} \left[\frac{i}{mn} - v_i\right]$$

respectively. On the other hand,  $S_3$  computes Smirnov statistics  $\hat{e}_1^{+}, \ldots, \hat{e}_m^{+}$  for each group separately.  $H_0$  is rejected by  $S_1$  if  $\hat{D}_1^{+} = [(m-\ell)n]^{\frac{1}{2}}d_1^{+}$  exceeds  $\hat{z}_{(m-\ell)n}(\alpha)$ , by  $S_2$  if  $\hat{D}_2^{+} = (mn)^{\frac{1}{2}}d_2^{+}$  exceeds  $\hat{z}_{mn}(\alpha)$ , and by  $S_3$  if max  $\sqrt{n}\hat{e}_k^+$  exceeds  $z_n(\alpha_m)$ . The caret signifies percentage points modified for parameter estimation. Interest centers on comparing the performance of  $S_2$  and  $S_3$ . The following theorem shows that in certain circumstances as the sample size becomes large,  $S_3$ 's power tends to one, but  $S_2$ 's tends to  $\alpha$ , the level of the test. This last result is proved by showing that, asymptotically,  $S_2$  can do no better than  $S_1$ .

Theorem 2: In the notation of Theorem 1 and the preceding paragraphs, suppose that in addition to Assumptions 1 and 2, the following conditions hold:

(i) 
$$\ell(n/m)^{\frac{1}{2}} \rightarrow 0 \text{ as } N \rightarrow \infty$$

(ii) Let  $h_N = \hat{\theta}(X_1, \dots, X_{mn}) - \hat{\theta}(X_1, \dots, X_{(m-\ell)n})$ , where  $X_i$   $(1 \le i \le (m-\ell)n)$  are iid as F and  $X_i$  $((m-\ell)n+1 \le i \le mn)$  are iid as G.  $h_N = o_P ((mn)^{-\frac{1}{2}})$ ,

(iii)  $G \neq F$ .

Then, as  $\mathbb{N} \rightarrow \infty$ ,

 $P\{S_2 \text{ rejects } H_0\} \rightarrow \alpha$ 

and

$$P\{S_3 \text{ rejects } H_0\} \rightarrow 1.$$

<u>Proof</u>: We first consider the case of  $H_0$  simple, so that no estimation is required, and develop a relation between  $d_1^+$  and  $d_2^+$ .

Suppose that  $t_j$  =  $v_{j+k}$  for some 1  $\leq$  j  $\leq$  (m-l)n and some 1  $\leq$  k  $\leq$  ln. Then

$$\left| \begin{array}{c} \left(\frac{\mathbf{j}+\mathbf{k}}{\mathbf{mn}} - \mathbf{v}_{\mathbf{j}+\mathbf{k}}\right) - \left(\frac{\mathbf{j}}{(\mathbf{m}-\ell)\mathbf{n}} - \mathbf{t}_{\mathbf{j}}\right) \right|$$
  
$$\leq \left| \begin{array}{c} \frac{\mathbf{j}}{\mathbf{mn}} - \frac{\mathbf{j}}{(\mathbf{m}-\ell)\mathbf{n}} \right| + \frac{\mathbf{k}}{\mathbf{mn}} \leq \frac{2\ell}{\mathbf{m}}.$$
(2.1)

That is, the discrepancies assigned by  $S_1$  and  $S_2$  to the same observation differ by, at most,  $2\ell/m$ . Of course,  $S_2$  must also compute the discrepancies at the  $\ell n$  observations not available to  $S_1$ . For fixed  $t_1, \ldots t_{(m-\ell)n}$ , the most extreme situation occurs when these  $\ell n$  observations are all less than  $t_1$  and, in this case, no discrepancy can exceed  $\ell/m$ .Consequently,

$$d_2^+ \leq d_1^+ + 3\ell/m,$$

so that

$$D_2^+ \leq \sqrt{\frac{m}{m-\ell}} D_1^+ + 3\ell \sqrt{\frac{n}{m}} . \qquad (2.2)$$

Thus, if  $\ell \sqrt{n/m} \rightarrow 0$  as the total sample size tends to infinity, then the power of S<sub>2</sub>'s test tends to  $\alpha$  and this remains the case no matter how distant the alternative.

On the other hand, under the conditions of the theorem,  $\sqrt{n} e_i^+ = 0_p(\sqrt{n})$  for each of the discordant groups. Since  $z_n(\alpha_m) = 0(\sqrt{\log m})$ ,  $S_3$  must have asymptotic power 1. This result holds even if one considers a sequence of alternatives converging to the null distribution at an appropriate rate.

The presence of nuisance parameters does not alter these conclusions for, corresponding to each observation x among the (m- $\ell$ ) groups conf<sub>Q</sub>rming to H<sub>0</sub>, we have for some  $1 \leq j \leq (m-\ell)n$  and some  $1 \leq k \leq \ell n$ ,

$$t_{j} = F(x, \hat{\theta}_{(m-\ell)n}^{(1)})$$

and

$$v_{j+k} = F(x, \hat{\theta}_{mn}^{(2)}),$$

where  $\hat{\theta}_{(m-\ell)n}^{(1)}$  and  $\hat{\theta}_{mn}^{(2)}$  are the estimates of  $\theta$  employed by  $S_1$  and  $S_2$ , respectively. Now,

$$\begin{aligned} \mathbf{t}_{j} - \mathbf{v}_{j+k} &= \left| \mathbf{F}(\mathbf{x}, \hat{\theta}_{(m-\ell)n}^{(1)}) - \mathbf{F}(\mathbf{x}, \hat{\theta}_{mn}^{(2)}) \right| \\ &\leq \left| \hat{\theta}_{(m-\ell)n}^{(1)} - \hat{\theta}_{mn}^{(2)} \right| \left| \frac{\partial \mathbf{F}(\mathbf{x}, \theta)}{\partial \theta} \right| \theta = \theta^{*}, \end{aligned}$$

where  $\theta^*$  lies between  $\hat{\theta}_{(m-\ell)n}^{(1)}$  and  $\hat{\theta}_{mn}^{(2)}$ . Hence,  $|t_j - v_{j+k}| = o_p((mn)^{-\frac{1}{2}})$  and (2.1) becomes

$$\left| \left[ (j+k)/mn - v_{j+k} \right] - \left[ j/(m-\ell)n - t_{j} \right] \right| \leq 2\ell/m + o_{p}((mn)^{-2}).$$
(2.3)

Thus,

$$\hat{D}_{2}^{+} \leq (m/(m-\ell))^{\frac{1}{2}} \hat{D}_{1}^{+} + 2\ell(n/m)^{\frac{1}{2}} + q_{p}(1), \qquad (2.4)$$

and, consequently, the power of  $S_2$ 's procedure must tend to  $\alpha$  as the sample size increases.

 $S_3$ 's estimate of  $\theta$  coincides with that of  $S_2$ 's and, hence, his estimate of the underlying distribution converges uniformly in probability to the null distribution. In fact,

$$|F(x, \hat{\theta}_{mn}^{(2)}) - F(x, \theta_0)| = \max \{0_p(\ell/m), 0_p([(m-\ell)n]^{-\frac{1}{2}})\}.$$

It is readily apparent that  $S_3$ 's power tends to 1, as the sample size increases, inasmuch as  $\sqrt{n} \hat{e}_i^+$  is still  $0_p(\sqrt{n})$  for the discordant groups.  $\Box$ 

<u>Remark</u>: Condition (ii) of the theorem must be verified in each particular application. It is certainly satisfied by the sample mean if F and G have finite expectations, since

$$\hat{\theta}_{mn} = \hat{\theta}_{(m-\ell)n} - (\ell/m) \hat{\theta}_{(m-\ell)n} + (\ell/m) \begin{bmatrix} mn \\ \Sigma \\ j = (m-\ell)n+1 \end{bmatrix} x_j/(\ell n)].$$

However, estimators satisfying Assumption 1 should, in general, be quite well behaved in this respect.

## C. Finite Sample Results

One may ask whether the asymptotic results of Theorem 2 are at all relevant to sample sizes common in practice. Since purely analytical methods are unlikely to prove tractable, a large-scale Monte Carlo study is needed to give an informative answer. However, the heuristic argument presented below does indicate that the suggested procedure should have good power, even in only moderately large samples. The argument is an indirect one, in that it does not involve the calculation of any rejection probabilities. Rather, it consists of studying a class of sample configurations which should be fairly typical under the alternative hypothesis. For such samples, it is possible to develop an approximate relation between the statistics computed by  $S_2$  and  $S_3$  from which we can derive some idea of the relative performance of the two procedures. Suppose that  $\ell = 1$ ; that is, of the m groups, exactly one does not conform to  $H_0$ , and that its distribution is stochastically smaller than that specified by  $H_0$ . After estimating the nuisance parameters, the two statisticians compute the two-sided Kolmogorov statistic on the transformed data. Let  $d_3$  denote the (unnormalized) statistic calculated by  $S_3$  for the discordant group,  $d_2$  denote the value of the statistic computed by  $S_2$  for the whole sample, and  $d_2^*$  the statistic based on the (m-1)n observations corresponding to the groups conforming to  $H_0$ . We propose to show that, roughly speaking,

$$d_2 \leq d_2^* + d_3^{m-1}.$$
 (2.5)

The argument is somewhat similar to the one in Theorem 2. Suppose that  $0 \leq t_1 \leq t_2 \leq \cdots \leq t_{(m-1)n}$  denote the observations for which  $d_2^*$  is calculated. Assuming that  $d_2^*$  is fairly typical, we construct samples which make  $d_2$  as large as possible consistent with the value of  $d_3$ . In reality, the different configurations of the discordant group affect the final sample configuration through their contribution to the parameter estimates. One aspect of the heuristic nature of the discussion is that this effect is ignored.

Assuming the t<sub>i</sub>'s to be fixed, d<sub>2</sub> becomes larger the smaller the observations in the discordant group. But if d<sub>3</sub> = n<sup>- $\gamma$ </sup> (say) for some  $\gamma \epsilon (0, \frac{1}{2})$ , then no more than about n<sup>1- $\gamma$ </sup> of these can be smaller than t<sub>1</sub>, without violating the constraint. The change in the discrepancy at t<sub>1</sub> is then no more than

$$\frac{n^{1-\gamma}+1}{mn} - \frac{1}{n(m-1)} \sim n^{-\gamma} m^{-1}.$$

If  $\boldsymbol{w}_n,$  the largest of these observations, falls between  $\boldsymbol{t}_{i-1}$  and

t, then the change in the discrepancy at t is (letting  $j = \alpha (m-1)n$ )

$$\frac{\alpha (m-1)n + n}{mn} - \alpha = \frac{1-\alpha}{m}.$$

But, since  $d_3 = n^{-\gamma}$ , we must have  $w_n \ge 1 - n^{-\gamma}$ . Thus,  $1 - \alpha$  should not, in general, exceed  $n^{-\gamma}$  so that  $(1-\alpha)/m \le n^{-\gamma} m^{-1}$ . Intuitively, these are the two extreme cases. If nothing unusual occours between  $t_1$  and  $t_{\alpha}$ , it should be true that

$$d_2 \leq d_2^* + n^{-\gamma} m^{-1},$$

for the discrepancies at the new observations can not exceed the RHS of the expression.

The "inequality" (2.5) is sharper than (2.1) and more useful for our present purposes because the bound for  $d_2$  involves the value of  $d_3$ . It is convenient to carry out the remainder of the discussion in terms of the modified versions of  $d_2$  and  $d_3$ (see Section 1.C). We therefore construct

$$\widetilde{D}_{3} = d_{3} (n^{\frac{1}{2}} + .12 + .11 n^{-\frac{1}{2}})$$
$$= n^{\frac{1}{2} - \gamma} + e_{3} (n) .$$
(2.6)

The modification of d<sub>2</sub> is more problematic inasmuch as the appropriate formula depends on the particular null hypothesis being tested. For the sake of convenience, we suppose that the null distribution is normal with unspecified mean and variance. (It should be emphasized that the general validity of the conclusions do not depend on this particular choice .) Employing the formula given in Pearson and Hartley [1972], page 359, we construct

$$\widetilde{D}_2 = d_2 ((nm)^{\frac{1}{2}} - 0.01 + 0.85 (nm)^{-\frac{1}{2}}).$$

In the sequel, we suppose that  $d_2$  assumes the upper bound given in (2.5) and, hence,

$$\widetilde{D}_{2} = (d_{2}^{*} + n^{-\gamma} m^{-1}) (nm)^{\frac{1}{2}} + (d_{2}^{*} + n^{-\gamma} m^{-1}) (- .01 + 0.85 (nm)^{-\frac{1}{2}}) = [(nm)^{\frac{1}{2}} d_{2}^{*} + n^{\frac{1}{2}-\gamma} m^{-\frac{1}{2}}] + e_{2} (n,m).$$
(2.7)

Consider a sequence of problems, indexed by n, in which  $(nm)^{\frac{1}{2}} d_2^{*}$  remains roughly constant. If  $\gamma$  is held fixed as n increases, then it follows from (2.6) and (2.7) that  $\widetilde{D}_3$  increases, but  $\widetilde{D}_2$  decreases. That is  $P_3$ , the P-value of  $\widetilde{D}_3$ , becomes more extreme, while  $P_2$ , the P-value of  $\widetilde{D}_2$ , becomes less extreme. Table I presents some numerical examples which show that in fairly typical situations  $P_2 > mP_3$ , indicating that the procedure based on  $\widetilde{D}_3$  provides a more sensitive test of  $H_0$ .

In view of Theorem 2, this last result is not very surprising, involving, as it does, increasingly extreme values of  $\widetilde{D}_3$ . However, a more informative comparison can be constructed in the following manner. Suppose  $\alpha$  is held fixed, but  $\gamma = \gamma(n)$  is allowed to vary with n, so that  $d_3 = n^{-\gamma(n)}$  is just significant at level  $\alpha_m$ . This is equivalent to considering a sequence of tests of fixed overall level  $\alpha$ . How then do the P-values of  $\widetilde{D}_2$  behave in this sequence of problems ?

Interestingly, the P-values increase (i.e. become less extreme), just as before. This follows from the fact, which we shall now prove, that  $\gamma(n)$  increases with n. If Z is a random variable distributed as  $\widetilde{D}_3$ , then the significance level corresponding to Z = z is

$$\alpha = \alpha(z) = 2 \exp(-2z^2)$$
. (2.8)

In our problem, approximating  $\alpha_{\rm m}$  by  $\alpha/m$ , (2.8) becomes  $\alpha/m(n) = 2 \exp \left[-2(n^{\frac{1}{2}-\gamma(n)} + e_3(n))^2\right]$ , whence

$$\gamma(n) = \frac{1}{2} - \log \left[ \left( -\frac{1}{2} \log \alpha / (2m(n)) \right)^{\frac{1}{2}} - e_{3}(n) \right] / \log n$$

which is an increasing function of n. Returning to (2.7), the crucial term in the expression for  $\tilde{D}_2$  is  $n^{-\gamma(n)} \frac{(n/m(n))^{\frac{1}{2}}}{(n/m(n))^{\frac{1}{2}}}$ . Under the hypotheses of our theorem, n/m(n) decreases in n. Since  $n^{-\gamma(n)}$  also decreases in n,  $\tilde{D}_2$  must decrease in n, as well. A numerical illustration can be found in Table II.

	-	LABLE I		
Comparison	of	P-values,	γ	fixes.

n	m	N	q <sub>n</sub>	D <sub>3</sub>	$\tilde{D}_2$	P3	mP <sub>3</sub>	P2
8	8	64	.415	1.776	1.238	$3.6 \times 10^{-3}$	$2.9 \times 10^{-2}$	7.0x10 <sup>-4</sup>
12	18	216	.368	1.943	1.055	1.05x10 <sup>-3</sup>	$1.9 \times 10^{-2}$	8.0x10 <sup>-3</sup>
16	32	512	.330	2.074	.954	3.68x10 <sup>-4</sup>	1.2 x10 <sup>-2</sup>	2.6x10 <sup>-2</sup>
20	50	1000	.295	2.183	.899	1.45x10 <sup>-4</sup>	7.25x10 <sup>-3</sup>	4.5x10 <sup>-2</sup>

#### TABLE II

		Comparison of P-values, overall level_fixed.						
n	γ(n)	$\widetilde{D}_2$	P <sub>2</sub>					
8	.250	1.238	7.0x10 <sup>-4</sup>					
12	.262	1.041	9.2x10 <sup>-3</sup>					
16	.271	.934	3.2x10 <sup>-2</sup>					
20	.277	.876	5.8x10 <sup>-2</sup>					

In carrying out the computations lefor g to Table I, n and m were chosen to satisfy the relations

$$n = 2N^{1/3}$$
 and  $m = N^{2/3}/2 = n^2/8$ .

In addition,  $\gamma$  was fixed to be .25 and  $(mn)^{\frac{1}{2}} d_2^*$  to be .6. That this choice of  $\gamma$  is a reasonable one for the sample sizes employed, can be inferred from the  $q_n$  column in Table I. The  $q_n$ are defined by

$$q_n = P\{\max_{1 \le i \le n} \Phi(X_i) \le 1 - n^{-25}\},$$

where  $\Phi$  is the df of a standard normal variate and  $X_1, \ldots X_n$  are iid N(-1.5,1). The values of  $q_n$  indicate that  $d_3 \ge n^{-.25}$  is not an uncommon occurance even for moderately distant alternatives. Finally, fixing  $d_2^* = .6/(mn)^{\frac{1}{2}}$  is roughly equivalent to locating  $d_2^*$  at the median of the distribution.

The column labelled  $mP_3$  gives the overall level of the procedure so that the computed value of  $\tilde{D}_3$  is just significant at level  $\alpha/m$ , leading to a rejection of  $H_0$  by  $S_3$ . This should be compared with the  $P_2$  column which contains the P-values of  $\tilde{D}_2$ . The rather extreme values of  $P_2$  for n = 8 and 12 are probably more due to the crudeness of the bound (2.5) for small sample sizes than to any particular merit of the procedure. Note that in contrast to  $mP_3$ ,  $P_2$  rapidly increases with n.

In Table II, the values of  $\gamma(n)$  were chosen to keep mP<sub>3</sub> fixed at 2.9x10<sup>-2</sup>, its value for n = 8 in Table I. Although P<sub>2</sub> decreases with n, the changes, in comparison with the corresponding values of Table I, are not as dramatic as those in mP<sub>3</sub>.

Taking n = 20 as an example, mP<sub>3</sub> changes from  $7.25 \times 10^{-3}$  to  $2.9 \times 10^{-2}$ , an increase by a factor of 4. On the other hand, P<sub>2</sub>

changes from  $4.5 \times 10^{-2}$  to  $5.8 \times 10^{-2}$ , an increase by a factor of only 1.5.

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