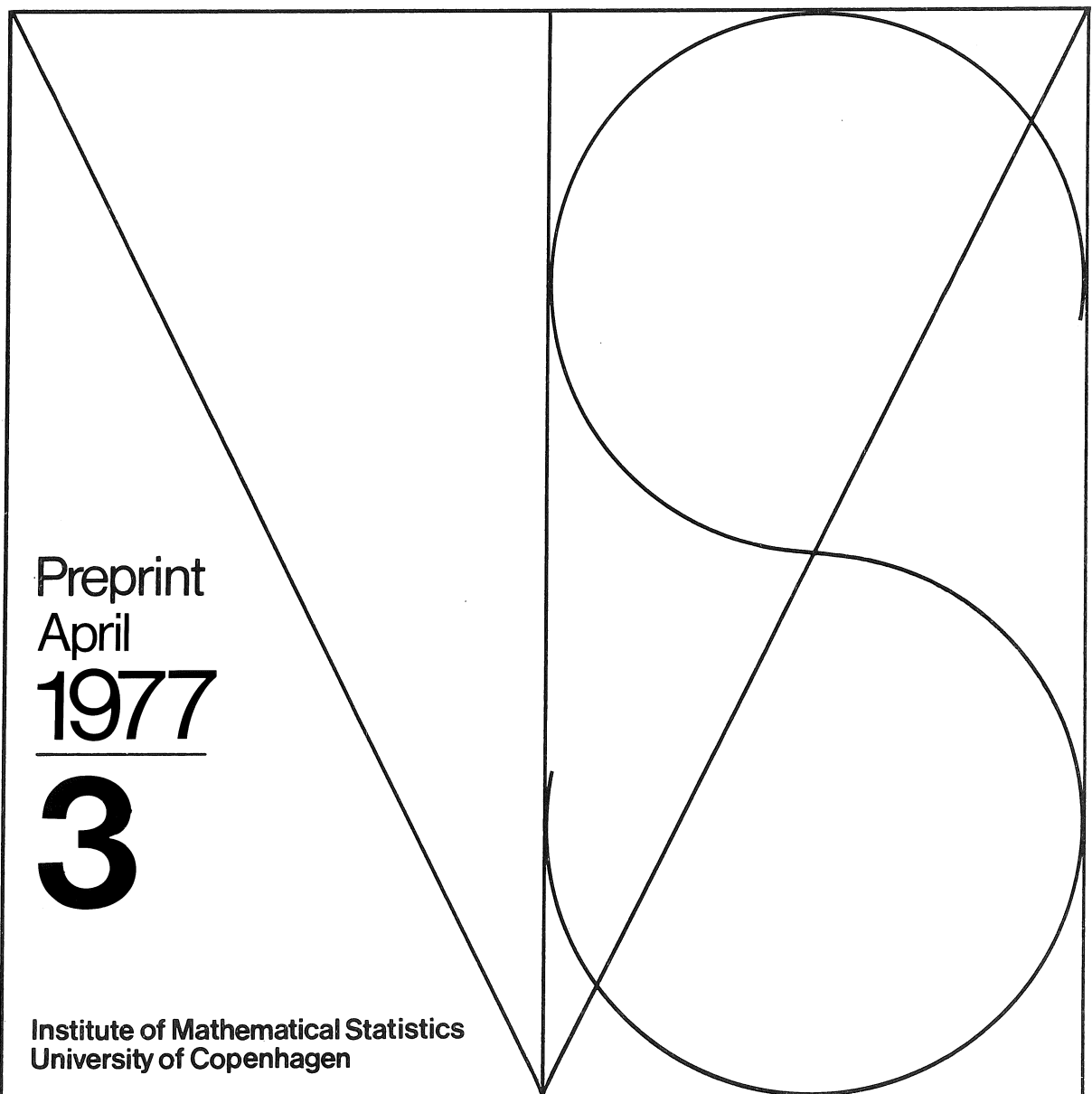


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and Markov Processes



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PRODUCT INTEGRALS AND MARKOV PROCESSES

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Product Integrals and Markov Processes

by

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1. Introduction. A finite state Markov Process is usually described by the Kolmogorov differential equations

$$(1.1) \quad \frac{\partial}{\partial t} P(s,t) = P(s,t)Q(t),$$

where $P(s,t)$ denotes the transition probabilities and $Q(t)$ the intensity matrix. The solution to (1.1) with initial condition $P(s,s) = I$ is given by the product integral

$$P(s,t) = \prod_s^t (I + Q(u) du)$$

For references to this, see Schlesinger (1931) and Dobrushin (1953). The product integral was used to study the imbedding problem by Johansen (1973). L u

In the study of the estimation problem for a nonhomogeneous Markov Process (Aalen and Johansen, 1977) it turned out that we needed the product-integral representation of a transition probability which is only piecewise constant. This note contains the definition of the product integral, where the measure $\int_A Q(u) du$ is replaced by an arbitrary matrix valued measure ν on $[0,1]$. bab

Section 2 contains the product integral and some of its properties and section 3 then applies this integral to the representation of the transition probabilities in terms of its

integrated intensities. We thus obtain a different approach to some of the results of Jacobsen (1972).

2. The Product Integral

Let \mathfrak{B} denote the Borel sets of $[0,1]$ and let ν be a σ -additive finite signed measure with values in the set of $n \times n$ matrices, i.e. a matrix of n^2 real measures. We let $\nu^{(n)}$ denote product measure on $[0,1]^n$ defined by

$$\nu^{(n)}(B_1 \times \dots \times B_n) = \nu(B_1) \dots \nu(B_n), B_i \in \mathfrak{B}.$$

We shall use the notation $\| \cdot \|$ to denote matrix norm

$$\|\nu(B)\| = \sup_i \sum_j |\nu_{ij}(B)|, \text{ and introduce the real positive measure}$$

$$\nu_0 = \sum_i \sum_j |\nu_{ij}|(B)$$

where $|\nu_{ij}| = \nu_{ij}^+ + \nu_{ij}^-$.

One easily checks, that $\|\nu(B)\| \leq \nu_0(B)$ and that

$$\|\nu^{(n)}(B_1 \times \dots \times B_n)\| \leq \prod_{i=1}^n \nu_0(B_i).$$

We now give the basic definition:

2.1. Definition. For $B \in \mathfrak{B}$ we define the product integral

$$\prod_B (I + d\nu) = I + \sum_{n=1}^{\infty} \nu^{(n)}(B \times \dots \times B \cap \{u_1 < \dots < u_n\}).$$

Notice that from the inequality

$$\|\nu^{(n)}(B \times \dots \times B \cap \{u_1 < \dots < u_n\})\| \leq$$

$$\nu_0^{(n)}(B \times \dots \times B \cap \{u_1 < \dots < u_n\}) \leq \frac{1}{n!} \nu_0(B)$$

follows the convergence of the series.

The following evaluations follow easily from the definition.

2.2. Proposition. For $B \in \mathfrak{B}$ we have

$$\begin{aligned} \|I + \nu(B)\| &\leq e^{\nu_0(B)} \\ \|\Pi(I+d\nu)\| &\leq e^{\nu_0(B)} \\ \|\Pi(I+d\nu) - I\| &\leq \nu_0(B) e^{\nu_0(B)} \\ \|\Pi(I+d\nu) - I - \nu(B)\| &\leq \frac{1}{2} \nu_0(B)^2 e^{\nu_0(B)} \end{aligned}$$

Now we can immediately prove the basic property of multiplicativity:

2.3. Theorem. For any $t \in [0,1]$ we have

$$\Pi_B(I+d\nu) = \Pi_{B \cap [0,t]}(I+d\nu) \Pi_{B \cap [t,1]}(I+d\nu) .$$

Thus $\Pi_B(I+d\nu)$ is multiplicative over disjoint intervals, which is the reason for its name.

Proof. For $i = 1, \dots, n-1$ let

$$A(B, i, n) = B \times \dots \times B \cap \{u_1 < \dots < u_i \leq t < u_{i+1} < \dots < u_n\}$$

with the obvious modification for $i = 0$ and n . We let

$$A(B, n) = B \times \dots \times B \cap \{u_1 < \dots < u_n\} = \bigcup_{i=0}^n A(B, i, n) .$$

Now

$$\begin{aligned} \nu(A(B, n)) &= \sum_{i=0}^n \nu(A(B, i, n)) \\ &= \sum_{i=0}^n \nu^{(i)}(A(B \cap [0,t], i)) \nu^{(n-i)}(A(B \cap [t,1]), n-i) . \end{aligned}$$

Summing over n gives the result.

2.4. Examples. If $d\nu = Qdt$, where Q is a fixed matrix then

$$\nu^{(n)}(0 \leq u_1 < \dots < u_n \leq t) = \frac{t^n Q^n}{n!}$$

and hence

$$\Pi_{[0,t]}(I+d\nu) = e^{tQ} .$$

If $dv = Q_1 dt$ for $0 \leq t \leq t_1$ and $dv = Q_2 dt$ for $t_1 < t \leq 1$, then using Theorem 2.3, and the above example, we get

$$\Pi_{[0,t]}(I+dv) = \begin{cases} e^{Q_1 t} & , 0 \leq t \leq t_1 , \\ e^{Q_1 t_1} e^{Q_2 (t-t_1)} & , t_1 < t \leq 1 . \end{cases}$$

As a final example we let $\nu = Q \varepsilon_{t_1}$ where Q is fixed and ε_{t_1} is a one point measure at t_1 , then

$$\Pi_{[0,t]}(I+dv) = \begin{cases} I & , 0 \leq t < t_1 , \\ I+Q & , t_1 \leq t \leq 1 . \end{cases}$$

Thus we get a piecewise constant function of t .

The following results give a different and perhaps more intuitive definition of the product integral. The definition we have chosen seems to give the basic results in a very efficient manner, since we can use existing integration and measure theory.

2.5. Theorem. Let $0 = t_0 < t_1 < \dots < t_n = 1$, then

$$\| \Pi_{[0,t]}(I+dv) - \prod_{i=0}^{n-1} (I+\nu]t_i, t_{i+1}] \| \leq c \sup_i \nu_0]t_i, t_{i+1}] .$$

Proof. We split the product integral into the corresponding factors and define

$$M_i = \Pi_{]t_i, t_{i+1}]}(I+dv) , N_i = I + \nu]t_i, t_{i+1}]$$

then by Proposition 2.2, we get

$$\|M_i\| \leq e^{\nu_0]t_i, t_{i+1}]} , \|N_i\| \leq e^{\nu_0]t_i, t_{i+1}]} .$$

We also get

$$\begin{aligned}
 \|M_i - N_i\| &= \left\| \prod_{]t_i, t_{i+1}[} (I + dv) (I + v[t_{i+1}]) - I - v[t_{i+1}] \right\| \\
 &\leq \left\| \prod_{]t_i, t_{i+1}[} (I + dv) - I - v[t_{i+1}] \right\| + \left\| \prod_{]t_i, t_{i+1}[} (I + dv) - I \right\| \|v[t_{i+1}]\| \\
 &\leq \frac{1}{2} (v_0]t_i, t_{i+1}[)^2 e^{v_0]t_i, t_{i+1}[} + v_0]t_i, t_{i+1}[e^{v_0]t_i, t_{i+1}[} \cdot v_0[t_{i+1}] \\
 &\leq e^{v_0]t_i, t_{i+1}[} (\sup_i v_0]t_i, t_{i+1}[) v_0]t_i, t_{i+1}[.
 \end{aligned}$$

Using these evaluations we get

$$\begin{aligned}
 \left\| \prod_{i=0}^{n-1} M_i - \prod_{i=0}^{n-1} N_i \right\| &\leq \sum_{i=0}^{n-1} \|M_0 \dots M_{i-1} (M_i - N_i) N_{i+1} \dots N_{n-1}\| \\
 &\leq e^{v_0[0,1]} (\sum_i v_0]t_i, t_{i+1}[) \sup_i v_0]t_i, t_{i+1}[
 \end{aligned}$$

as was the result we wanted to prove.

2.6. Corollary. Let t_{in} satisfy the conditions

a) $0 = t_{0n} < t_{1n} < \dots < t_{nn} = 1$

and

b) $\lim_{n \rightarrow \infty} \sup_i v_0]t_{in}, t_{(i+1)n}[= 0,$

then the product integral can be computed as

$$\prod_{]0,1]} (I + dv) = \lim_{n \rightarrow \infty} \prod_{i=0}^{n-1} (I + v]t_{in}, t_{(i+1)n}[)$$

Notice that condition b) can always be satisfied, since we can make sure that the atoms of v (i.e. of v_0) eventually are among the division points.

The next results are about differentiability of the product integral.

2.7. Theorem. For $B \in \mathfrak{B}$ we have

$$\Pi(I+dv) - I = \int_B \Pi_{B \cap [0, u[} (I+dv) v(du)$$

Proof. Using Fubini's theorem on the $(n+1)$ 'st term we get

$$\begin{aligned} & v^{(n+1)}(B \times \dots \times B, 0 \leq u_1 < \dots < u_{n+1} \leq 1) \\ &= \int_B v^{(n+1)}(B \times \dots \times B, 0 \leq u_1 < \dots < u_{n+1} \leq 1 | u_{n+1} = u) v(du) \\ &= \int_B v^{(n)}(B \times \dots \times B, 0 \leq u_1 < \dots < u_n < u) v(du) . \end{aligned}$$

Summing over n gives the result.

2.8. Theorem. For $B \in \mathfrak{B}$ we have

$$\Pi(I+dv) - I = \int_B v(du) \Pi_{[u, 1] \cap B} (I+dv)$$

Proof. Similar to that of Theorem 2.7. If we define the function

F by

$$t \rightarrow \Pi_{[0, t]} (I+dv)$$

then F is right continuous by Theorem 2.7 and it is of bounded variation. It thus determines a matrix valued measure, which by Theorem 2.7 is absolutely continuous with respect to ν_0 . The integral relation can thus be reformulated as

$$\frac{dF}{d\nu_0}(t) = F(t^-) \frac{d\nu}{d\nu_0}, \text{ a.s. } [\nu_0] .$$

If $H : t \rightarrow \Pi_{[t, 1]} (I+dv)$, then Theorem 2.8 can be reformulated as

$$\frac{dH}{d\nu_0}(t) = - \frac{d\nu}{d\nu_0}(t) H(t) , \text{ a.s. } [\nu_0] .$$

3. Markov Processes

In constructing a Markov Process one can start with the transition probabilities, satisfying the Chapman-Kolmogorov equations, then construct the process, i.e. the measure on a suitable function space, by the Kolmogorov consistency theorem, see Doob (1953), or via a general theorem of extension of continuous linear functionals, see Nelson (1959), or Goodman and Johansen (1973). In this case the discussion of the differential equations for the transition probabilities becomes a discussion of when a process is determined by its infinitesimal properties.

One can also start out with the waiting time distributions and the jump intensities and then construct the measure very directly, and then prove that certain variables form a Markov Process and define the transition probabilities in terms of these. The differential equations can now be viewed as a convenient and different way of obtaining the transition probabilities, see Jacobsen (1972).

We shall here start with the intensities or rather the integrated intensities ν , i.e. we assume that

$$\nu_{ii} \leq 0, \nu_{ij} \geq 0, i \neq j \text{ and } \sum_j \nu_{ij} = 0.$$

From this measure we construct the transition probabilities by a product integral and this also gives us the differential equations for P . Thus the approach is highly non-probabilistic as opposed to that of Jacobsen (1972). The solution, however, is the same, as we shall show.

Thus, we let ν be finite signed measure on $[0,1]$ with

values in the set of intensity matrices, then the following holds:

3.1. Theorem. If $\nu[t] + I$ is a stochastic matrix, i.e. if $\nu_{ii}[t] \geq -1$, then

$$P(B) = \prod_B (I + d\nu)$$

is a stochastic matrix.

Proof. Assume first that $\nu_{ii}[t] > -1$, $i = 1, \dots, n$, i.e. no atoms of ν are as large as -1 . Then let us choose the partition t_{in} of $[0,1]$ so fine that $I + \nu]_{t_{in}, t_{(i+1)n}}$ is a stochastic matrix. By Corollary 2.6 $P(B)$ is the limit of stochastic matrices, hence stochastic.

In general there can only be a finite number of points t_1, \dots, t_k , such that some $\nu_{ii}[t_r] = -1$. By writing

$$P(B) = (I + \nu(0)) \cdot \prod_{i=1}^{k-1} \prod_{B \cap]t_i, t_{i+1}[} (I + d\nu) (I + \nu[t_{i+1}])$$

we see that $P(B)$ is stochastic.

For a given ν we now define

$$P(s, t) = P(]s, t]) = \prod_{]s, t]} (I + d\nu), \quad 0 < s < t \leq 1,$$

$$P(0, t) = P([0, t]) = \prod_{[0, t]} (I + d\nu), \quad 0 \leq t \leq 1,$$

then it is seen that $P(s, t)$ is right continuous in s and t (except for $s = 0, t \downarrow 0$), and that

$$P(t^-, t) = I + \nu[t], \quad 0 < t \leq 1$$

$$P(t, t^+) = I, \quad 0 < t < 1$$

$$P(0, 0^+) = I + \nu[0].$$

The multiplicativity of the product integral now immediately gives that $P(s,t)$ satisfies the Chapman-Kolmogorov equations

$$P(s,t) = P(s,u)P(u,t) \quad 0 \leq s < u < t \leq 1,$$

and in this formulation, Theorem 2.7 gives the forward differential equation

$$\frac{\partial P(s,t)}{\partial v_0(t)} = P(s,t) \frac{dv}{dv_0}(t) \quad \text{a.s. } [v_0]$$

whereas Theorem 2.8 gives the backward equation

$$\frac{\partial P(s,t)}{\partial v_0(s)} = - \frac{dv}{dv_0}(s) P(s,t) \quad , \text{ a.s. } [v_0]$$

which show that $P(s,t)$ do infact have v as integrated intensity measure.

Using a result similar to Theorem 2.5 one can prove that for $s < t_{on} < \dots < t_{nn} = t$ such that $\sup_i v_0]^{t_{in}, t_{(i+1),n}} \rightarrow 0$ we have

$$\prod_{[s,t]} (1+dv_{kk}) = \lim_{n \rightarrow \infty} \prod_{i=0}^{n-1} (1+P_{kk}]^{t_{in}, t_{(i+1),n}})$$

which is nothing but the waitingtime distribution in state i , i.e.

$$P\{X_u = i, s < u \leq t | X_s = i\} = \prod_{[s,t]} (1+dv_{ii}).$$

With the notation

$$G_i[0,t] = 1 - \prod_{[0,t]} (1+dv_{ii})$$

and

$$\pi_{ij}(t) = - \frac{dv_{ij}}{dv_{ii}}(t), \quad i \neq j, \quad \pi_{ij}(t) = 0$$

we can now prove that the solution provided by Jacobsen,

starting with G and π is in fact the same as the solution provided here starting from v .

Notice that v can be recovered from G and π , by the relations

$$v_{ii}(A) = - \int_A \frac{G_i(du)}{1-G_i[0,u[}$$

and

$$v_{ij}(A) = - \int_A \pi_{ij}(u) v_{ii}(du).$$

We shall now assume, that v satisfies the following extra conditions

- 1) $v[0] = 0$
- 2) $v_{ii}[t] > -1$.

i.e. $P(s,t)$ becomes right continuous, also at 0, and no atom is as large as -1 .

It is then seen that G_i is continuous at zero, and that $G_i[0,t] = 0$ if $v_{ii}[0,t] = 0$ and that $G_i[0,t] \leq 1$, since $v_{ii}[0,1]$ is finite. In order to see the last result, where condition 2) is needed, we argue as follows: The largest atom of $|v_{ii}|$ is $1-\varepsilon$ say. Now choose $0 = t_0 < \dots < t_n = 1$ such that $|v_{ii}[t_j, t_{j+1}[| < \frac{\varepsilon}{2}$ then

$$1+v_{ii}[t_j, t_{j+1}[> \frac{\varepsilon}{2}$$

and $\log(1+v_{ii}[t_j, t_{j+1}[) \geq \frac{\log \frac{\varepsilon}{2}}{-1 + \frac{\varepsilon}{2}} v_{ii}[t_j, t_{j+1}[$.

Summing over j gives

$$\prod_j \Pi(1+v_{ii}[t_j, t_{j+1}]) \geq c > 0$$

which again implies that $\prod_B \Pi(1+dv_{ii}) \geq c > 0$.

Thus the functions G and π satisfy the conditions of Jacobsen and his solution $\tilde{P}(s,t)$ is constructed to satisfy the integral equation:

obs!

$$\tilde{p}_{ij}(s,t) = \delta_{ij} \frac{G_i[t,1]}{G_i[s,1]} + \sum_{k \neq i} \int_{[s,t]} \pi_{ik}(u) \tilde{p}_{kj}(u,t) \frac{G_i(du)}{G_i[s,1]}.$$

Using the definition of (G, π) in terms of ν this is

$$(3.1) \quad \tilde{p}_{ij}(s,t) = \delta_{ij} \frac{\prod (1+dv_{ii})}{[s,t]} - \sum_{k \neq i} \int_{[s,t]} \tilde{p}_{kj}(u,t) \frac{\prod (1+dv_{ii}) \nu_{ik}(du)}{[s,u]}$$

which is known to have a unique solution, see Feller (1940).

The function $P[s,t] = \frac{\prod (1+dv)}{[s,t]}$ is known to satisfy the equation

$$(3.2) \quad p_{ij}(s,t) - \delta_{ij} = \sum_k \int_{[s,t]} \nu_{ik}(du) p_{kj}(u,t).$$

In this equation we multiply by $\frac{\prod (1+dv_{ii})}{[a,s]}$ and integrate with respect to $\nu_{ii}(ds)$. If we then use the results:

$$\int_{[a,t]} \frac{\prod (1+dv_{ii}) \nu_{ii}(ds)}{[a,s]} = \frac{\prod (1+dv_{ii})}{[a,t]} - 1$$

and

$$\int_{[a,u]} \frac{\prod (1+dv_{ii}) \nu_{ii}(ds)}{[a,s]} = \frac{\prod (1+dv_{ii})}{[a,u]} - 1$$

then we get after some reduction that P also satisfies equation (3.1), hence $P = \tilde{P}$.

In fact the equations (3.1) and (3.2) are equivalent. If (3.1) is integrated with respect to $v_{ii}(ds)$ on $[a,t]$, we arrive at (3.2).

It should of course be pointed out that we are only dealing with a finite number of states, whereas Jacobsen treats the more general situation of a countable number of states.

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