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A GENERALIZATION OF THE CRAMÉR-RAO INEQUALITY

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## INTRODUCTION

The famous Cramér-Rao inequality (Rao [1945], Cramér [1946]) gives a lower bound for the variance of unbiased estimators. By generalizing the concept of a mean-value one is led to consider new concepts of unbiasedness. It is shown that in these cases an inequality similar to the inequality of Cramér-Rao holds, providing a lower bound to a quantity which can be interpreted as the measure of dispersion corresponding to the particular choice of mean-value.

The joint results of the authors were first collected in Harder Hansen [1961].

### 1. Generalized Mean-Values.

In this section we list the properties of generalized mean-values which are needed in the following. For proofs see Brøns [1967], comp. Brøns, Brunk, Franck, and Hanson [1969].

Let  $g$  be a convex function on the open interval  $J$  on  $\mathbb{R}$  (the set of real numbers), and consider the sets

$$V_g = \{\tau \in J \mid g(\tau') \geq g(\tau) \forall \tau' \leq \tau\}, \quad H_g = \{\tau \in J \mid g(\tau') \geq g(\tau) \forall \tau' \geq \tau\}.$$

$V_g$  is empty or an interval with the same left endpoint as  $J$ , and  $H_g$  is empty or an interval with same right endpoint as  $J$ .

The set  $V_g \cap H_g$  is either empty or an interval, and is the set of points in which  $g$  assumes its minimum. Its left endpoint is denoted  $m_0g$  and its right endpoint  $m_1g$ . Both values can be infinite. If  $H_g$  is empty,  $m_0g$  is the right endpoint of  $J$ , and if  $V_g$  is empty  $m_1g$  is the left endpoint of  $J$ . The identity

$$\{\tau \in J \mid m_0g \leq \tau\} = \{\tau \in J \mid D^+g(\tau) \geq 0\}$$

and the similar one for  $m_1$  and  $D^-g$  characterize  $m_0$  and  $m_1$  in terms of  $g$ 's left and right derivatives  $D^-g$  and  $D^+g$ .

Let  $\mathcal{A}$  be a  $\sigma$ -field on a set  $X$ . A C-function on  $X$  is a function  $g: X \times J \rightarrow \mathbb{R}$  such that the partial function  $x \mapsto g(x, \tau)$  is  $\mathcal{A}$ -measurable for all  $\tau \in J$  and the partial function  $\tau \mapsto g(x, \tau)$  is convex for all  $x \in X$ .

Let  $D^-g(x, \tau)$  denote the left derivative and  $D^+g(x, \tau)$  the right derivative in  $\tau$  of the convex function  $\tau \mapsto g(x, \tau)$ . Then the functions  $x \mapsto D^-g(x, \tau)$  and  $x \mapsto D^+g(x, \tau)$  are  $\mathcal{A}$ -measurable functions for all  $\tau \in J$ , and the function  $x \mapsto g(x, \tau) - g(x, \theta)$  is integrable with respect to a probability measure  $P$  on  $\mathcal{A}$  for all  $(\tau, \theta) \in J^2$  if and only if  $x \mapsto D^-g(x, \tau)$  (or  $x \mapsto D^+g(x, \tau)$ ) are  $P$ -integrable for all  $\tau \in J$ . When the integrals exist the function

$$h(\tau) = \int (g(x, \tau) - g(x, \theta)) P(dx)$$

is convex for all  $\theta \in J$  and

$$D^-h(\tau) = \int D^-g(x, \tau) P(dx), \quad D^+h(\tau) = \int D^+g(x, \tau) P(dx).$$

$m_0h$  and  $m_1h$  are independent of  $\theta$ .

$P$  is said to have unique  $g$ -mean-value $^\theta$  if  $m_0h = m_1h = \theta$ .  $P$  has regular  $g$ -mean-value, if  $h$  also is twice differentiable in  $\theta$  with positive second derivative, and the function  $x \mapsto D^+g(x, \tau)$  further has positive second moment for all  $\tau \in J$ .

## 2. The Generalized Cramér-Rao Inequality.

Let  $\lambda$  be a measure on  $\mathcal{A}$ , and  $(P_\theta)_{\theta \in \Theta}$  a family of probability measures on  $\mathcal{A}$  with the open interval  $\Theta \subset J$  as parameter space.  $P_\theta$  is supposed to be absolutely continuous with respect to  $\lambda$  with finite density  $x \mapsto f(x, \theta)$ . We put  $l(x, \theta) = -\log f(x, \theta)$ .

The family  $(P_\theta)_{\theta \in \Theta}$  is said to be smooth if

- i) The function  $\theta \mapsto l(x, \theta)$  is absolutely continuous with respect to

Lebesgue measure and has Radon-Nikodym derivative  $Dl(x, \theta)$  for all  $x \in X$

ii)  $0 < \int (Dl(x, \theta))^2 f(x, \theta) \lambda(dx) < +\infty$  for all  $\theta \in \Theta$ .

iii) For  $\tau$  tending decreasingly to  $\theta$

$$\frac{f(x, \theta) - f(x, \tau)}{(\tau - \theta) f(x, \theta)}$$

will tend to  $Dl(x, \theta)$  in quadratic mean with respect to  $P_\theta$ .

Theorem. Assume that  $P_\theta$  has the regular  $g$ -mean-value  $\theta$  for all  $\theta \in \Theta$ , and let  $\gamma(\theta)$  denote the second derivative of the function  $h_\theta: J \rightarrow \mathbb{R}$   $\tau \mapsto \int (g(x, \tau) - g(x, \theta)) f(x, \theta) \lambda(dx)$  taken in the point  $\theta$ . If the family  $(P_\theta)_{\theta \in \Theta}$  is smooth

$$(1) \quad \frac{\int (D^+g(x, \theta))^2 f(x, \theta) \lambda(dx)}{\gamma^2(\theta)} \geq \frac{1}{\int (D^+l(x, \theta))^2 f(x, \theta) \lambda(dx)}$$

for all  $\theta \in \Theta$ . Here the equality sign is valid if and only if there exists a function  $k: \Theta \rightarrow \mathbb{R}$  such that  $\tau \mapsto D^+g(x, \tau)k(\tau)$  is locally integrable for all  $x \in X$  and such that

$$(2) \quad f(x, \tau) = f(x, \theta) e^{-\int_\theta^\tau D^+g(x, \xi) k(\xi) d\xi}$$

for  $\tau$  and  $\theta$  in  $\Theta$ .

Proof. Since  $D^-h_\theta(\tau) > 0$  for  $\tau < \theta$ ,  $D^+h_\theta(\tau) < 0$  for  $\tau < \theta$ ,  $D^-h_\theta(\theta) \leq D^+h_\theta(\theta)$  and  $D^-h_\theta$  and  $D^+h_\theta$  are continuous in the point  $\theta$  it follows that  $D^-h_\theta(\theta) = D^+h_\theta(\theta) = 0$ .

Therefore

$$\int D^-g(x, \theta) P_\theta(dx) = \int D^+g(x, \theta) P_\theta(dx)$$

and so  $D^-g(x, \theta) = D^+g(x, \theta)$  with  $P_\theta$ -probability one.

Since  $\tau \mapsto D^+g(x, \tau)$  is decreasing  $(D^+g(x, \tau) - D^+g(x, \theta))^2$  will tend decreasingly to 0 for  $\tau \downarrow \theta$ , i.e.  $D^+g(x, \tau)$  tends to  $D^+g(x, \theta)$  in quadratic mean with respect to  $P_\theta$ . Since

$$\frac{1}{\tau - \theta} \int D^+g(x, \tau) f(x, \theta) \lambda(dx) = \int D^+g(x, \tau) \frac{f(x, \theta) - f(x, \tau)}{(\tau - \theta) f(x, \theta)} f(x, \theta) \lambda(dx)$$

it follows that

$$\gamma(\theta) = \int D^+g(x, \theta) D^+l(x, \theta) f(x, \theta) \lambda(dx).$$

Applying Cauchy-Schwarz's inequality one finds that

$$(3) \quad \gamma^2(\theta) \leq \int (D^+g(x, \theta))^2 f(x, \theta) \lambda(dx) \int (D^+l(x, \theta))^2 f(x, \theta) \lambda(dx)$$

which proves (1).

Equality holds in (3) if and only if for each  $\theta \in \Theta$  there exists a constant  $k(\theta)$  such that  $D^+l(x, \theta) = D^+g(x, \theta)k(\theta)$ .

Since  $\theta \mapsto l(x, \theta)$  is absolutely continuous it follows that

$$l(x, \tau) - l(x, \theta) = \int_\theta^\tau D^+g(x, \xi) k(\xi) \lambda(d\xi)$$

which is the same as (2).

### 3. Unbiased Estimation.

Let  $g$  be a C-function on  $R$  and  $t : X \rightarrow R$  an  $\mathcal{A}$ -measurable function.

The function  $g_t : (x, \theta) \mapsto g(t(x), \theta)$  is a C-function on  $X$ .

$t$  is said to be a g-unbiased estimator if  $P_\theta$  has the unique  $g_t$ -meanvalue  $\theta$

for all  $\theta \in \Theta$ .  $t$  is a regular g-unbiased estimator if  $\theta$  is a regular  $g_t$ -mean-value for all  $\theta \in \Theta$ .

The theorem shows that if  $t$  is a regular  $g$ -unbiased estimator and the family  $(P_\theta)_{\theta \in \Theta}$  is smooth then

$$(4) \quad V_\theta(t) = \frac{\int (D^+g(t(x), \theta))^2 f(x, \theta) \lambda(dx)}{\gamma_{g_t}(\theta)^2} \geq \frac{1}{\int (Dl(x, \theta))^2 f(x, \theta) \lambda(dx)}$$

with equality if and only if

$$f(x, \tau) = f(x, \theta) e^{-\int_\theta^\tau D^+g(t(x), \xi) k(\xi) d\xi}.$$

Example 1. For

$$g(x, \theta) = \frac{(x - \theta)^2}{2}, \quad (x, \theta) \in \mathbb{R}^2$$

the probability  $P$  on  $\mathbb{A}$  has a unique  $g_t$ -mean-value  $\theta$  if and only if  $\int t(x)P(dx)$  exists, is finite and equal to  $\theta$ . This meanvalue is regular when  $t$  has finite variance and

$$V_\theta(t) = \int (t(x) - \theta)^2 f(x, \theta) \lambda(dx).$$

(4) reduces in this way to the well-known Cramér-Rao inequality. Equality holds if and only if

$$f(x, \tau) = f(x, \theta) e^{-\int_\theta^\tau k(\xi) d\xi + t(x) \int_\theta^\tau k(\xi) d\xi},$$

in which case the family is exponential.

Example 2. For

$$g(x, \theta) = \begin{cases} \frac{1}{p}(\theta - x) & \text{for } x \leq \theta \\ \frac{1}{q}(x - \theta) & \text{for } x \geq \theta \end{cases}$$

where  $0 < p = 1 - q \leq 1$ ,  $P$  has a unique  $g_t$ -mean-value if and only if

$t$  has the unique  $p$ -quantile  $\theta$ . This mean-value is regular when the distribution function for  $t$  is differentiable in  $\theta$  with positive derivative  $k(\theta)$  and

$$V_{\theta}(t) = \frac{pq}{k^2(\theta)} .$$

(4) provides a lower bound for  $V_{\theta}(t)$  for  $p$ -quantile unbiased estimators. This bound is equivalent to an upper bound to the height  $k(\theta)$  of the density of  $t$  in  $\theta$ .  $p = \frac{1}{2}$  corresponds to median-unbiasedness.

The examples illustrate how  $V(t)$  in general provides a natural measure of dispersion corresponding to a specific concept of unbiasedness. The theorem chap. IX, p.9-10 in Brøns [1967] shows that the asymptotic variance of empirical  $g$ -mean-values are proportional to  $V(t)$ .

#### References.

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