

Suppose some tangent vectors  $\mathbf{v} \in T_P\mathcal{S}$  and  $\mathbf{w} \in T_Q\mathcal{S}$  at different points  $P, Q$  of a surface are given. It is a natural question to ask when  $\mathbf{v}$  and  $\mathbf{w}$  should be considered parallel. If  $\mathcal{S}$  is a plane, the answer is obvious, the tangent vectors are parallel if and only if they are parallel when considered as vectors in  $\mathbb{R}^3$ . However, for other surfaces the tangent spaces  $T_P\mathcal{S}$  and  $T_Q\mathcal{S}$  are not equal, and a more sophisticated notion has to be introduced. In fact, a reasonable definition only exists if a curve is given that connects  $P$  and  $Q$ . The notion of parallelism between vectors in  $T_P\mathcal{S}$  and  $T_Q\mathcal{S}$  will in general depend on the curve.

Let  $\gamma$  be a regular curve on  $\mathcal{S}$ . A (tangent) *vector field*  $\mathbf{V}$  *along*  $\gamma$  is a smooth map which to each  $t$  assigns a vector  $\mathbf{V}(t) \in \mathbb{R}^3$  such that  $\mathbf{V}(t) \in T_{\gamma(t)}\mathcal{S}$ . We will define the notion of parallelism of such a vector field. For simplicity we consider only vector fields of constant length  $\|\mathbf{V}(t)\|$ .

**Definition 1.** A vector field  $\mathbf{V}(t)$  along  $\gamma$  of constant length is called *parallel* if the derivative  $\dot{\mathbf{V}}(t)$  is normal to the tangent plane  $T_P\mathcal{S}$  at each point  $P = \gamma(t)$  of the curve.

The idea is that since the tangent space varies along  $\gamma$ , the vector field is forced to vary too, but we require that this variation is invisible from the surface. Thus a parallel vector field will be conceived as constant by a resident of the surface (a surface bug).

Notice that the condition that  $\dot{\mathbf{V}}(t)$  is normal to the tangent plane for each  $t$  implies that  $\frac{d}{dt}(\mathbf{V} \cdot \mathbf{V}) = 2\dot{\mathbf{V}} \cdot \mathbf{V} = 0$ . The condition of constant length is thus actually a consequence of the other condition.

In our further analysis we will assume throughout that  $\mathcal{S}$  is oriented, so that a unit normal vector  $\mathbf{N}$  is given at each point.

**Example.** The unit tangent vectors to a great circle on a sphere form a parallel vector field. This is easily seen by simple geometric considerations, but it also follows from the next lemma.

**Lemma 1.** *A unit speed curve  $\gamma$  on  $\mathcal{S}$  is a geodesic if and only if its tangent vectors  $\dot{\gamma}(t)$  form a parallel field.*

*Proof.* Immediate from Definition 8.1.  $\square$

The definition of a parallel vector field makes use of the extrinsic concept of the normal to the surface. However, the discussion after the definition suggests that it is *intrinsic*. Indeed, this follows from the next proposition, since it expresses the concept in terms of the first fundamental form alone (see Note 9).

**Proposition 1.** *Let  $\gamma$  be a regular curve on an orthogonal patch  $(\sigma, U)$  of  $\mathcal{S}$ , and let  $\mathbf{V}(t)$  be a vector field along  $\gamma$  with constant non-zero length. Let  $\varphi(t)$  be a differentiable determination of the angle from  $\sigma_u$  to  $\mathbf{V}(t)$ . Then  $\mathbf{V}$  is parallel if and only if*

$$\dot{\varphi} = \frac{1}{2\sqrt{EG}} \{ \dot{u}E_v - \dot{v}G_u \} \tag{1}$$

*at each point of the curve.*

*Proof.* As in Note 9, let

$$\mathbf{X} = \frac{\sigma_u}{\sqrt{E}} \quad \text{and} \quad \mathbf{Y} = \frac{\sigma_v}{\sqrt{G}},$$

then at each point  $P$  of  $\sigma(U)$ , the triple  $(\mathbf{X}, \mathbf{Y}, \mathbf{N})$  constitutes a positively oriented orthonormal basis for  $\mathbb{R}^3$ . It was shown in Note 9, page 3, that  $\mathbf{X} \cdot \dot{\mathbf{Y}}$  is equal to the expression on the right side of (1).

Let

$$\hat{\mathbf{V}}(t) = \mathbf{N}(t) \times \mathbf{V}(t),$$

then  $(\mathbf{V}, \hat{\mathbf{V}}, \mathbf{N})$  is also a positively oriented orthonormal basis for  $\mathbb{R}^3$ , at each point of  $\gamma$ . Since  $\mathbf{V}$  has constant length,  $\dot{\mathbf{V}} \perp \mathbf{V}$ . Hence  $\dot{\mathbf{V}}$  is a linear combination of  $\hat{\mathbf{V}}$  and  $\mathbf{N}$ , and it is perpendicular to the tangent space if and only if the component along  $\hat{\mathbf{V}}$  vanishes. Therefore,  $\mathbf{V}$  is parallel if and only if  $\dot{\mathbf{V}} \cdot \hat{\mathbf{V}} = 0$ .

We claim that

$$\dot{\mathbf{V}} \cdot \hat{\mathbf{V}} = -\mathbf{X} \cdot \dot{\mathbf{Y}} + \dot{\varphi},$$

clearly this implies the statement of the proposition, in view of the preceding remarks.

By definition of  $\varphi(t)$  we have

$$\mathbf{V} = \cos \varphi \mathbf{X} + \sin \varphi \mathbf{Y}. \quad (2)$$

Hence

$$\hat{\mathbf{V}} = -\sin \varphi \mathbf{X} + \cos \varphi \mathbf{Y}. \quad (3)$$

By differentiating (2) with respect to  $t$  and inserting (3) we obtain

$$\dot{\mathbf{V}} = -\dot{\varphi} \sin \varphi \mathbf{X} + \cos \varphi \dot{\mathbf{X}} + \dot{\varphi} \cos \varphi \mathbf{Y} + \sin \varphi \dot{\mathbf{Y}} = \dot{\varphi} \hat{\mathbf{V}} + \cos \varphi \dot{\mathbf{X}} + \sin \varphi \dot{\mathbf{Y}}$$

Using that  $\dot{\mathbf{X}} \perp \mathbf{X}$  and  $\dot{\mathbf{Y}} \perp \mathbf{Y}$  we conclude

$$\begin{aligned} \dot{\mathbf{V}} \cdot \hat{\mathbf{V}} &= \dot{\varphi} + (\cos \varphi \dot{\mathbf{X}} + \sin \varphi \dot{\mathbf{Y}}) \cdot (-\sin \varphi \mathbf{X} + \cos \varphi \mathbf{Y}) \\ &= \dot{\varphi} + \cos^2 \varphi \dot{\mathbf{X}} \cdot \mathbf{Y} - \sin^2 \varphi \dot{\mathbf{Y}} \cdot \mathbf{X}. \end{aligned}$$

Notice that from  $\mathbf{X} \cdot \mathbf{Y} = 0$  we obtain  $\dot{\mathbf{X}} \cdot \mathbf{Y} + \mathbf{X} \cdot \dot{\mathbf{Y}} = 0$ . Hence

$$\dot{\mathbf{V}} \cdot \hat{\mathbf{V}} = \dot{\varphi} - \cos^2 \varphi \mathbf{X} \cdot \dot{\mathbf{Y}} - \sin^2 \varphi \dot{\mathbf{Y}} \cdot \mathbf{X} = \dot{\varphi} - \mathbf{X} \cdot \dot{\mathbf{Y}}. \quad \square$$

**Corollary 1.** *Let  $\mathbf{V}$  and  $\mathbf{W}$  be vector fields along  $\gamma$  of constant non-zero length, and suppose that  $\mathbf{V}$  is parallel. Then  $\mathbf{W}$  is parallel if and only if its angle with  $\mathbf{V}$  is constant.*

*Proof.* If the vector fields make the angles  $\varphi(t)$  and  $\psi(t)$  with  $\sigma_u$ , then  $\varphi$  satisfies equation (1). Hence  $\psi$  satisfies the same equation if and only if  $\dot{\psi} = \dot{\varphi}$ , that is, if and only if the difference  $\psi - \varphi$  is constant. The angle between  $\mathbf{V}$  and  $\mathbf{W}$  is exactly measured by that difference.  $\square$

**Proposition 2.** Let  $\gamma$  be a unit speed curve on  $\mathcal{S}$ , and let  $\mathbf{V}(t)$  be a vector field along  $\gamma$  of constant non-zero length. Let  $\delta(t)$  be a differentiable determination of the angle from  $\dot{\gamma}(t)$  to  $\mathbf{V}(t)$ . Then  $\mathbf{V}$  is parallel if and only if

$$\dot{\delta} = -\kappa_g$$

at each point of the curve.

*Proof.* We consider the curve in a neighborhood of a given point, and we may assume that this neighborhood is contained in an orthogonal patch. As in Prop. 1, let  $\varphi$  be the angle from  $\sigma_u$  to  $\mathbf{V}(t)$ , then  $\theta = \varphi - \delta$  measures the angle from  $\sigma_u$  to  $\dot{\gamma}(t)$ . The proposition is obtained by combining Proposition 1 with the proposition in Note 9.  $\square$

**Corollary 2.** If  $\gamma$  is a geodesic, then a vector field  $\mathbf{W}$  is parallel along  $\gamma$  if and only if its angle with  $\dot{\gamma}$  is constant.

*Proof.* Since  $\gamma$  is a geodesic,  $\kappa_g = 0$ .  $\square$

The last corollary tells us exactly which vector fields are parallel along a geodesic. However, if  $\gamma$  is not a geodesic, it is a priori not clear whether there exist at all any parallel vector fields along it. This we will now show. In fact, we can uniquely determine a parallel vector field along  $\gamma$  from any given tangent vector at some initial point:

**Proposition 3.** Let  $\gamma : I \rightarrow \mathcal{S}$  be a unit speed curve on  $\mathcal{S}$ , and let  $t_0 \in I$ ,  $\mathbf{v} \in T_{\gamma(t_0)}\mathcal{S}$  be given. Then there exists a unique parallel vector field  $\mathbf{V}(t)$  along  $\gamma$  of constant length and with  $\mathbf{V}(t_0) = \mathbf{v}$ .

*Proof.* We may assume  $\mathbf{v} \neq 0$  (otherwise take  $\mathbf{V}(t) = 0$ ). Let  $\delta_0$  be the angle from  $\dot{\gamma}(t_0)$  to  $\mathbf{v}$  and define

$$\delta(t) = \delta_0 - \int_{t_0}^t \kappa_g(s) ds.$$

Let  $\mathbf{V}(t)$  be the unit vector field along  $\gamma(t)$  which makes the angle  $\delta(t)$  with  $\dot{\gamma}(t)$ . Then it follows from Prop. 2 that  $\mathbf{V}$  is parallel. The uniqueness is seen similarly.  $\square$

Let  $P = \gamma(t_0)$  and  $Q = \gamma(t_1)$  be points on  $\gamma$ . Using Prop. 3 we define the map

$$T : T_P\mathcal{S} \rightarrow T_Q\mathcal{S},$$

which assigns to  $\mathbf{v} \in T_P\mathcal{S}$  the vector  $T(\mathbf{v}) = \mathbf{V}(t_1) \in T_Q\mathcal{S}$ , where  $\mathbf{V}$  is the parallel vector field with  $\mathbf{V}(t_0) = \mathbf{v}$ . The map is called *parallel transport* along  $\gamma$ .

**Definition 2.** Two vectors  $\mathbf{v} \in T_P\mathcal{S}$  and  $\mathbf{w} \in T_Q\mathcal{S}$  are said to be *parallel* with respect to  $\gamma$  if  $\mathbf{w}$  is the parallel transport along  $\gamma$  of  $\mathbf{v}$ .

**Lemma 2.** Parallel transport is linear  $T_P\mathcal{S} \rightarrow T_Q\mathcal{S}$ .

*Proof.* It suffices to prove the following. If  $\mathbf{V}$  and  $\mathbf{W}$  are parallel vector fields along the same curve  $\gamma$ , then the vector field  $t \mapsto \lambda\mathbf{V}(t) + \mu\mathbf{W}(t)$  is also parallel, for all  $\lambda, \mu \in \mathbb{R}$ . This follows easily from Definition 1.  $\square$

**Example** Let  $\mathcal{S} = S^2$ , and let  $\gamma$  be the parallel circle of constant latitude  $u = u_0$  (see p. 61), where  $\sigma(u, v) = (\cos u \cos v, \cos u \sin v, \sin u)$ . Let  $a = \cos u_0$ ,  $b = \sin u_0$  then

$$\gamma(t) = \sigma(u_0, t) = (a \cos t, a \sin t, b)$$

is a (non unit speed) parametrization of  $\gamma$ . Let  $P = \gamma(0) = \sigma(u_0, 0) = (a, 0, b)$ . We will determine the parallel transport along  $\gamma$  of the vector  $\mathbf{v} = \sigma_u = (-b, 0, a) \in T_P\mathcal{S}$ . If  $\varphi$  is the angle from  $\sigma_u(\gamma(t))$  to the vector  $\mathbf{V}(t)$  of the parallel field, then by Prop. 1

$$\dot{\varphi} = b = \sin u_0$$

(because  $u(t) = u_0$ ,  $v(t) = t$ ,  $E = 1$ ,  $G = \cos^2 u$ ). Since  $\varphi(0) = 0$  we obtain

$$\varphi(t) = bt.$$

In particular, when at  $t = 2\pi$  the curve returns to the initial point  $P$ , the vector  $\mathbf{v}$  has been displaced by the angle

$$\varphi(2\pi) - \varphi(0) = 2\pi b = 2\pi \sin u_0.$$