Note 8. Geodesics as shortest curves.

This note contains a simplification of the proof of Theorem 8.2. We follow the proof on p. 192-194, but replace the expressions involving E, F, G by expressions involving the goedesic curvature κ_q . Equation (14) reads,

$$\frac{d}{d\tau}\mathcal{L}(\tau) = \frac{1}{2}\int_{a}^{b} g(\tau, t)^{-1/2} \frac{\partial g}{\partial \tau} dt,$$

where $g(\tau, t) = \|\dot{\gamma}^{\tau}\|^2 = \dot{\gamma}^{\tau} \cdot \dot{\gamma}^{\tau}$. Since γ has unit speed, $g(\tau, t) = 1$ for $\tau = 0$. Hence

$$\frac{d}{d\tau}\mathcal{L} = \frac{1}{2} \int_{a}^{b} \frac{\partial g}{\partial \tau} dt, \quad \text{when } \tau = 0.$$

Now $\frac{\partial g}{\partial \tau} = 2 \frac{\partial^2 \gamma^{\tau}}{\partial \tau \partial t} \cdot \frac{\partial \gamma^{\tau}}{\partial t}$, hence using integration by parts

$$\frac{d}{d\tau}\mathcal{L} = \left[\frac{\partial\gamma^{\tau}}{\partial\tau} \cdot \frac{\partial\gamma^{\tau}}{\partial t}\right]_{a}^{b} - \int_{a}^{b} \frac{\partial\gamma^{\tau}}{\partial\tau} \cdot \frac{\partial^{2}\gamma^{\tau}}{\partial t^{2}} dt.$$

Since $\gamma^{\tau}(a)$ and $\gamma^{\tau}(b)$ are independent of τ (being equal to **p** and **q**, respectively), we have

$$\frac{\partial \gamma^{\gamma}}{\partial \tau} = 0$$
 when $t = a$ or $t = b$.

Hence the first term on the right-hand side is zero. Since $\gamma^{\tau}(t) \in \mathcal{S}$ for all τ , we have $\frac{\partial \gamma^{\tau}}{\partial \tau} \in T_P \mathcal{S}$ where $P = \gamma^{\tau}(t)$. Hence in the dot product in the second term we can replace $\ddot{\gamma}^{\tau} = \frac{\partial^2 \gamma^{\tau}}{\partial t^2}$ by its orthogonal projection on $T_P \mathcal{S}$. For $\tau = 0$ this equals $\kappa_g \mathbf{N} \times \dot{\gamma}$ (see p. 127, eq. (5)). In conclusion,

$$\frac{d}{d\tau}\mathcal{L} = -\int_{a}^{b} \frac{\partial \gamma^{\tau}}{\partial \tau} \cdot \kappa_{g}(\mathbf{N} \times \dot{\gamma}) dt, \quad \text{when } \tau = 0.$$

In particular, if γ is a geodesic, then $\kappa_g = 0$ and we conclude that $\frac{d}{d\tau}\mathcal{L} = 0$.

For the converse, we now have to show that if

$$\int_{a}^{b} \frac{\partial \gamma^{\tau}}{\partial \tau} \cdot \kappa_{g}(\mathbf{N} \times \dot{\gamma}) \, dt = 0$$

at $\tau = 0$, for all families of curves γ^{τ} , then $\kappa_g = 0$. Let $\gamma(t) = \sigma(u(t), v(t))$ and $\mathbf{N} \times \dot{\gamma}(t) = f(t)\sigma_u + g(t)\sigma_v$. Let $\phi(t)$ be an arbitrary smooth function defined for $a \leq t \leq b$ such that $\phi(a) = \phi(b) = 0$, and define for τ sufficiently close to 0

$$\gamma^{\tau}(t) = \sigma(u(t) + \tau\phi(t)f(t), v(t) + \tau\phi(t)g(t)).$$

Then γ^{τ} is a family of the required type, and

$$\frac{\partial \gamma^{\prime}}{\partial \tau} = \phi(t)f(t)\sigma_u + \phi(t)g(t)\sigma_v = \phi(t)(\mathbf{N} \times \dot{\gamma}(t))$$

for $\tau = 0$. Hence

$$0 = \int_{a}^{b} \phi(\mathbf{N} \times \dot{\gamma}) \cdot \kappa_{g}(\mathbf{N} \times \dot{\gamma}) dt = \int_{a}^{b} \phi \kappa_{g} dt,$$

because $\|\mathbf{N} \times \dot{\gamma}(t)\| = 1$. Since ϕ was arbitrary, it follows easily that $\kappa_g = 0$ (choose, for example, $\phi(t) = (t-a)(b-t)\kappa_g(t)$, so that $\phi\kappa_g \ge 0$).

HS

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