Parameter transformations – LDA

Fixing the last group K as a reference group we have for $k = 1, \ldots, K-1$ that

$$\log \frac{\Pr(Y=k|X=x)}{\Pr(Y=K|X=x)} = \underbrace{\log \frac{\pi_k}{\pi_K} + \frac{1}{2}\mu_K^T\Sigma^{-1}\mu_K - \frac{1}{2}\mu_k^T\Sigma^{-1}\mu_k}_{\beta_{k0}} + x^T \underbrace{\Sigma^{-1}(\mu_k - \mu_K)}_{\beta_k}$$

Thus

$$\Pr(Y=k|X=x) = \frac{\exp(\beta_{k0} + x^T\beta_k)}{1 + \sum_{l=1}^{K-1}\exp(\beta_{l0} + x^T\beta_l)}$$

for $k = 1, \ldots, K-1$. The conditional distribution depends upon $\pi_1, \ldots, \pi_{K-1}, \mu_1, \ldots, \mu_k, \Sigma$ through the parameter transformation

$$(\pi_1, \ldots, \pi_{K-1}, \mu_1, \ldots, \mu_K, \Sigma) \mapsto (\beta_{10}, \ldots, \beta_{(K-1)0}, \beta_1, \ldots, \beta_{K-1}).$$

Logistic Regression

We consider $K = 2$ and encode the y-variable as 0 or 1. The *logistic regression model* is given by

$$\Pr(Y = 1 \mid X = x) = \frac{\exp((1, x^T)\beta)}{1 + \exp((1, x^T)\beta)}$$

Hence

$$\Pr(Y = 0 \mid X = x) = 1 - \frac{\exp((1, x^T)\beta)}{1 + \exp((1, x^T)\beta)} = \frac{1}{1 + \exp((1, x^T)\beta)}.$$

We saw that the conditional distribution of Y given X in the LDA setup is a logistic regression model.

Figure 4.12 – South African Heart Disease Data

A typical use of *logistic regression*. The response variable is Myocardial Infarction. The two cases (0/1) are color coded in the plot.

The plot reveals pair-wise – and marginal – effects of the 7 observed variables on MI.

And clear correlations between `obesity` and `sbp` (systolic blood pressure), say.

Logistic Regression – Notation

Given a dataset $(y_1, x_1), \ldots, (y_N, x_N)$ write

$$\mathbf{p}(\beta) = (p_i(\beta))_{i=1}^N, \quad p_i(\beta) = \frac{\exp((1, x_i^T)\beta)}{1 + \exp((1, x_i^T)\beta)}.$$

With $h : \mathbb{R}^N \to \mathbb{R}^N$

$$h_i(z) = -\log(1 + \exp(z_i))$$

and taking coordinatewise logarithm

$$\log \mathbf{p}(\beta) = \mathbf{X}\beta + h(\mathbf{X}\beta)$$

and

$$\log(\mathbf{1} - \mathbf{p}(\beta)) = h(\mathbf{X}\beta)$$

Logistic Regression – The Minus-Log-Likelihood Function

The (conditional) likelihood function of observing $y_1, \ldots, y_N$ given $x_1, \ldots, x_N$ is

$$\mathcal{L}(\beta) = \prod_{i=1}^{N} p_i(\beta)^{y_i}(1 - p_i(\beta))^{1-y_i}$$

and the minus-log-likelihood function is

$$\begin{aligned} l(\beta) &= -\mathbf{y}^T(\mathbf{X}\beta + h(\mathbf{X}\beta)) - (\mathbf{1} - \mathbf{y})^T h(\mathbf{X}\beta) \\ &= -\mathbf{y}^T\mathbf{X}\beta - \mathbf{1}^T h(\mathbf{X}\beta) \end{aligned}$$

Observe that $D_z h(z)$ is diagonal with

$$D_z h(z)_{ii} = -\frac{\exp(z_i)}{1 + \exp(z_i)}$$

Logistic Regression – The MLE

By differentiation

$$\begin{aligned} D_\beta l(\beta) &= -\mathbf{y}^T\mathbf{X} - \mathbf{1}^T D_z h(\mathbf{X}\beta)\mathbf{X} \\ &= -\mathbf{y}^T\mathbf{X} + \mathbf{p}(\beta)^T\mathbf{X} \\ &= (\mathbf{p}(\beta)^T - \mathbf{y}^T)\mathbf{X} \end{aligned}$$

and

$$D_\beta^2 l(\beta) = D_\beta \mathbf{p}(\beta)^T\mathbf{X} = \mathbf{X}^T\mathbf{W}(\beta)\mathbf{X}$$

with

$$\begin{aligned} \mathbf{W}(\beta) &= \operatorname{diag}(\mathbf{p}(\beta))\operatorname{diag}(1 - \mathbf{p}(\beta)) \\ &= \begin{Bmatrix} p_1(\beta)(1 - p_1(\beta)) & \ldots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \ldots & p_N(\beta)(1 - p_N(\beta)) \end{Bmatrix} \end{aligned}$$

Likelihood Equation

The non-linear likelihood estimation equation reads (after transposition)

$$\mathbf{X}^T\mathbf{p}(\beta) = \mathbf{X}^T\mathbf{y}$$

Since $D_\beta^2 l(\beta) = \mathbf{X}^T\mathbf{W}(\beta)\mathbf{X}$ is *positive definite* whenever $\mathbf{X}$ has full rank $p + 1$, the minus-log-likelihood function is strictly convex and a minimum is unique.

There is *no solution* if the x-values for the two groups can be separated completely by a hyperplane.

Logistic Regression – Algorithm

A first order Taylor expansion

$$\mathbf{p}(\beta) \simeq \mathbf{p}(\beta^0) + \mathbf{W}(\beta^0)\mathbf{X}(\beta - \beta^0)$$

around β^0 yields the approximating equation

$$\mathbf{X}^T\mathbf{W}(\beta^0)\mathbf{X}\beta = \mathbf{X}^T\mathbf{W}(\beta^0)(\underbrace{\mathbf{X}\beta^0 + \mathbf{W}(\beta^0)^{-1}(\mathbf{y} - \mathbf{p}(\beta^0))}_{\text{adjusted response}=\mathbf{z}_0}).$$

The solution is precisely the solution of the *weighted least squares problem*

$$\underset{\beta}{\operatorname{argmin}}\ (\mathbf{z}_0 - \mathbf{X}\beta)^T\mathbf{W}(\beta^0)(\mathbf{z}_0 - \mathbf{X}\beta)$$

Iteration yielding a sequence β^n, $n \geq 0$, is known as the *iterative reweighted least squares* algorithm – or IRLS – using the *adjusted response*

$$\mathbf{z}_n = \mathbf{X}\beta^n + \mathbf{W}(\beta^n)^{-1}(\mathbf{y} - \mathbf{p}(\beta^n))$$

in the $(n+1)$'th iteration. The algorithm is equivalent to the Newton-Raphson algorithm.

Multinomial Regression and LDA

It is possible to formulate a multinomial version of the binary logistic regression model.

The algorithm for estimation becomes more complicated.

LDA relies on MLE for the full parameter in the full distribution of (X, Y). Logistic/multinomial regression relies on MLE in the conditional distribution of $Y \mid X$.

Logistic regression makes fewer distributional assumptions. Deviations from normality *could* affect LDA in the negative direction.

If the distributional assumptions for LDA are fulfilled, LDA is a little more efficient.

Penalized logistic regression

With $J : \mathbb{R}^{p+1} \to [0, \infty)$ we can consider the penalized minus-log-likelihood

$$l(\beta) + \lambda J(\beta).$$

If $J(\beta) = \sum_{i=1}^p \beta_i^2$ or $J(\beta) = \sum_{i=1}^p |\beta_i|$ there is always a minimizer.

Efficient algorithms (especially for lasso in the R package `glmnet`) are based on iterations that solve a penalized weighted least squares problem.

As for the two suggested penalty functions above we generally won't penalize the intercept parameter. It is optional to center the x-variables before computing the fit, but we can't get rid of the intercept parameter as in the least squares case by just centering the y-variables. It has to stay in the model. It is generally recommended to scale the x-variables to have unit empirical variance to bring them on a common scale. This is done internally by default in `glmnet`, but the resulting parameters are always transformed back to the original scale.

Large p Small N Problems

When $p > N$ and in particular when $p \gg N$ new issues arise.

- We are never able to estimate all parameters without regularization. E.g. in a regression there are p parameters but the $\mathbf{X}$-matrix only has rank N.
- Signals can drown in noise.
- Big matrices, computational challenges.

As a rule of thumb; choose simple methods over complicated methods when $p \gg N$, regularize and bet on "sparsity".

Figure 18.1

Simulation study with $Y = \sum_{i=1}^{p} \beta_j X_j + \sigma\varepsilon$.

Diagonal or Independence LDA

Recall that the estimated LDA classifier can be determined by

$$\delta_k(x) = \log \pi_k - \frac{1}{2}(x - \hat{\mu}_k)^T \hat{\Sigma}^{-1}(x - \hat{\mu}_k)$$

and we classify to $\text{argmax}_k\{\delta_k(x)\}$.

If

$$\hat{\Sigma} = \text{diag}(s_1^2, \ldots, s_p^2)$$

this simplifies to

$$\delta_k(x) = -\sum_{j=1}^{p} \frac{(x_j - \bar{x}_{kj})^2}{s_j^2} + 2\log \pi_k$$

where $x = (x_1, \ldots, x_p)^T$ and

$$\bar{x}_{kj} = \frac{1}{N_k} \sum_{i:y_i=k} x_{ij}$$

is the average of the j'th coordinate in the k'th group.

Shrunken Centroids

Note that the variance of $\bar{x}_{kj} - \bar{x}_j$ is

$$m_k^2\sigma^2 \quad \text{with} \quad m_k^2 = \frac{1}{N_k} - \frac{1}{N}.$$

Introduce the general *shrunken centroids*

$$\bar{x}'_{kj} = \bar{x}_j + m_k(s_j + s_0)g\left(\frac{\bar{x}_{kj} - \bar{x}_j}{m_k(s_j + s_0)}\right)$$

with s_0 a small, positive constant.

$$g_\Delta(d) = \text{sign}(d)(|d| - \Delta)_+$$

is known as *soft thresholding.*

$$g_\Delta(d) = d1(|d| \geq \Delta)_+$$

as *hard thresholding.*

The research report *Maximum likelihood classification in macroarray studies* by Jens Ledet Jensen is available here: http://www.imf.au.dk/publications/rr/2006/imf-rr-2006-474.pdf

Figure 18.4 – Train and Test Error

The parameter Δ is a tuning parameter for shrunken centroids. With 43 genes, $\Delta = 4.3$, we get a training error of 0 – but also a test error of 0.

Figure 18.4 – Centroid Profiles and Shrunken Centroids

Figure 18.3 – Heat Map

Elastic Net

The penalization function

$$\sum_{j=1}^{p} \alpha|\beta_j| + (1-\alpha)\beta_j^2$$

is known as the *elastic net penalty.*

For multinomial regression the penalized minus-log-likelihood function is

$$-\sum_{i=1}^{N} \log \Pr(Y = y_i | X = x_i) + \lambda \sum_{k=1}^{K} \sum_{j=1}^{p} \alpha|\beta_{kj}| + (1-\alpha)\beta_{kj}^2$$

There is an efficient implementation in the `glmnet` package for R.

Note that intercepts are not penalized and subject to the constraint that they sum to 0. All other redundancies in the parameterization are dealt with by the penalization.

Regularized Discriminant Analysis

Choosing the estimator

$$\hat{\Sigma}(\alpha) = \alpha\hat{\Sigma} + (1-\alpha)\text{diag}(\hat{\Sigma})$$

for $\alpha \in [0,1]$ we get a *regularized* covariance estimator usable for LDA.

The `rda` function in the `rda` library does this in combination with nearest shrunken centroids with `regularization="R"`. With `regularization="S"` one gets

$$\hat{\Sigma}(\alpha) = \alpha\hat{\Sigma} + (1-\alpha)I_p$$

It is a little unclear which of three suggested centroid shrinkage methods from the paper Guo et al. (2006), see book, that is implemented in the R package `rda`.

The following is a very brief intro to support vector machines. They are covered in more details in Chapter 12, but we wont read that chapter.

Support Vector Classifiers

Support vector machines are popular two class classifiers and have a reputation for being among the best performing.

With $y_i \in \{-1,1\}$, $x_i \in \mathbb{R}^p$ and $f : \mathbb{R}^p \to \mathbb{R}$ we compute the predictor of y_i as $\text{sign}(f(x_i))$. With f in a *reproducing kernel Hilbert space* $\mathcal{H}$ estimation is done by minimization of

$$\sum_{i=1}^{N}[1-y_i f(x_i)]_+ + \lambda||f||^2_{\mathcal{H}}$$

Thus the loss function $L : \{-1,1\} \times \mathbb{R} \to \mathbb{R}$ is special and given as

$$L(y,z) = [1-yz]_+ = \max\{1-yz, 0\}$$

Support Vector Classifiers – example

Simplest example: $\mathcal{H} = \mathbb{R}^{p+1}$ and $f(x) = x^T\beta + \beta_0$ for $\beta \in \mathbb{R}^p$. Hence the objective is minimization of

$$\sum_{i=1}^{N}[1-y_i(x_i^T\beta+\beta_0)]_+ + \lambda\sum_{i=0}^{p}\beta_i^2.$$

This problem can be equivalently formulated as a constraint optimization problem; minimize

$$\sum_{i=0}^{p}\beta_i^2 + C\sum_{i=1}^{N}\xi_i$$

subject to $\xi_i \geq 0$ and $y_i(x_i^T\beta+\beta_0) \geq 1-\xi_i$ for $i = 1,\ldots,N$.

Support vector machines are implemented in the R package `e1071` as the function `svm`.

The kernel trick

A reproducing kernel Hilbert space is characterized by a *kernel*, $K(x, x')$, which is *reproducing*:

$$\langle K(\cdot, x), K(\cdot, x') \rangle = K(x, x').$$

Solutions to the optimization problem above take the form

$$f(x) = \sum_{i=1}^{N} \alpha_i K(x, x_i).$$

The problem reduces to optimization of

$$\sum_{i=1}^{N} [1 - y_i (\mathbf{K}\alpha)_i]_+ + \lambda \alpha^T \mathbf{K} \alpha$$

where $\mathbf{K}_{ij} = K(x_i, x_j)$.

This is the *kernel trick*, which can reduce a high-dimensional problem (dimension $p \gg N$) to a reasonable sized problem of dimension N.

The complete characterization of reproducing kernel Hilbert spaces in terms of the kernel is that for any function f in the Hilbert space

$$f(x) = \langle K(\cdot, x), f \rangle,$$

that is, function evaluations at a given point are given in terms of inner products with $K(\cdot, x)$. This implies that if ρ is a function orthogonal to the functions $K(\cdot, x_i)$ for $i = 1, \ldots, N$ then $\rho(x_i) = \langle K(\cdot, x_i), \rho \rangle = 0$. This implies, together with Pythagorus, that solutions to the optimization problem (for any choice of loss function) have the finite expansion in terms of the kernel above. In this case, the optimization problem reduces as stated above. Indeed, the norm of such an f is

$$\begin{aligned} ||f||^2_{\mathcal{H}} &= \langle f, f \rangle \\ &= \sum_{i=1}^{N} \sum_{j=1}^{N} \alpha_i \alpha_j \langle K(\cdot, x_i), K(\cdot, x_j) \rangle \\ &= \sum_{i=1}^{N} \sum_{j=1}^{N} \alpha_i \alpha_j K(x_i, x_j) \\ &= \alpha^T \mathbf{K} \alpha. \end{aligned}$$

The solution is typically sparse in α and those x_i with $\alpha_i \neq 0$ are called *support vectors*.

Kernel examples

- $K(x, x') = x^T x'$ – the *linear* kernel.
- $K(x, x') = (1 + \gamma x^T x')^d$ – the *polynomial kernel*.
- $K(x, x') = \exp(-\gamma ||x - x'||^2)$ – the *radial basis kernel*.
- $K(x, x') = \tanh(\kappa_1 x^T x' + \kappa_2)$ – the *sigmoid* or *neural network* kernel.

Except for the linear kernel the kernels have, in addition to the penalization parameter, one or two other tuning parameters.