

A Noncommutative Gauss Map

Caleb Eckhardt

Université de Franche-Comté à Besançon

January 25, 2010, University of Copenhagen

Continued Fractions

Continued Fractions

- Let $0 < \alpha < 1$ be irrational.

Continued Fractions

- Let $0 < \alpha < 1$ be irrational.
- Recall there is a unique sequence $(a_n) \subseteq \mathbb{Z}^+$ with

Continued Fractions

- Let $0 < \alpha < 1$ be irrational.
- Recall there is a unique sequence $(a_n) \subseteq \mathbb{Z}^+$ with

$$\frac{p_n}{q_n} := \cfrac{1}{a_1 + \cfrac{1}{a_2 + \cfrac{1}{a_3 + \cfrac{1}{\ddots + \cfrac{1}{a_n}}}}}$$

Continued Fractions

- Let $0 < \alpha < 1$ be irrational.
- Recall there is a unique sequence $(a_n) \subseteq \mathbb{Z}^+$ with

$$\frac{p_n}{q_n} := \cfrac{1}{a_1 + \cfrac{1}{a_2 + \cfrac{1}{a_3 + \cfrac{1}{\ddots + \cfrac{1}{a_n}}}}}$$

- such that $\alpha = \lim_{n \rightarrow \infty} \frac{p_n}{q_n}$.

Continued Fractions

- Let $0 < \alpha < 1$ be irrational.
- Recall there is a unique sequence $(a_n) \subseteq \mathbb{Z}^+$ with

$$\frac{p_n}{q_n} := \cfrac{1}{a_1 + \cfrac{1}{a_2 + \cfrac{1}{a_3 + \cfrac{1}{\ddots + \cfrac{1}{a_n}}}}}$$

- such that $\alpha = \lim_{n \rightarrow \infty} \frac{p_n}{q_n}$.
- We write $\alpha = [a_1, a_2, \dots]$ in its **continued fraction decomposition**.

Continued Fractions

- Let $0 < \alpha < 1$ be irrational.
- Recall there is a unique sequence $(a_n) \subseteq \mathbb{Z}^+$ with

$$\frac{p_n}{q_n} := \cfrac{1}{a_1 + \cfrac{1}{a_2 + \cfrac{1}{a_3 + \cfrac{1}{\ddots + \cfrac{1}{a_n}}}}}$$

- such that $\alpha = \lim_{n \rightarrow \infty} \frac{p_n}{q_n}$.
- We write $\alpha = [a_1, a_2, \dots]$ in its **continued fraction decomposition**.
- This provides a nice, algorithmic approximation of irrational numbers by rational numbers.

Classical Gauss Map

Classical Gauss Map

- The Gauss map $G : [0, 1] \rightarrow [0, 1]$ is defined as

$$G(\alpha) = \begin{cases} 0 & \text{if } \alpha = 0 \\ 1/x - \lfloor 1/x \rfloor & \text{if } \alpha \neq 0 \end{cases}$$

Classical Gauss Map

- The Gauss map $G : [0, 1] \rightarrow [0, 1]$ is defined as

$$G(\alpha) = \begin{cases} 0 & \text{if } \alpha = 0 \\ 1/x - \lfloor 1/x \rfloor & \text{if } \alpha \neq 0 \end{cases}$$

- Then G is a Bernoulli shift for continued fractions.

Classical Gauss Map

- The Gauss map $G : [0, 1] \rightarrow [0, 1]$ is defined as

$$G(\alpha) = \begin{cases} 0 & \text{if } \alpha = 0 \\ 1/x - \lfloor 1/x \rfloor & \text{if } \alpha \neq 0 \end{cases}$$

- Then G is a Bernoulli shift for continued fractions.
-

$$G([a_1, a_2, a_3, \dots]) = G\left(\frac{1}{a_1 + \frac{1}{a_2 + \frac{1}{a_3 \dots}}}\right)$$

Classical Gauss Map

- The Gauss map $G : [0, 1] \rightarrow [0, 1]$ is defined as

$$G(\alpha) = \begin{cases} 0 & \text{if } \alpha = 0 \\ 1/x - \lfloor 1/x \rfloor & \text{if } \alpha \neq 0 \end{cases}$$

- Then G is a Bernoulli shift for continued fractions.
-

$$G([a_1, a_2, a_3, \dots]) = G\left(\frac{1}{a_1 + \frac{1}{a_2 + \frac{1}{a_3 \dots}}}\right)$$

Classical Gauss Map

- The Gauss map $G : [0, 1] \rightarrow [0, 1]$ is defined as

$$G(\alpha) = \begin{cases} 0 & \text{if } \alpha = 0 \\ 1/x - \lfloor 1/x \rfloor & \text{if } \alpha \neq 0 \end{cases}$$

- Then G is a Bernoulli shift for continued fractions.
-

$$\begin{aligned} G([a_1, a_2, a_3, \dots]) &= G\left(\frac{1}{a_1 + \frac{1}{a_2 + \frac{1}{a_3 \dots}}}\right) \\ &= a_1 + \frac{1}{a_2 + \frac{1}{a_3 \dots}} - a_1 = [a_2, a_3, \dots]. \end{aligned}$$

Gauss' Problem

Gauss' Problem

- Let m denote Lebesgue measure and define

$$m_n(x) = m(G^{-n}[0, x])$$

Gauss' Problem

- Let m denote Lebesgue measure and define

$$m_n(x) = m(G^{-n}[0, x])$$

- In an 1812 letter to Laplace, Gauss stated that he had shown that

Gauss' Problem

- Let m denote Lebesgue measure and define

$$m_n(x) = m(G^{-n}[0, x])$$

- In an 1812 letter to Laplace, Gauss stated that he had shown that
- $m_n(x) \rightarrow \frac{\ln(1+x)}{\ln 2}$ as $n \rightarrow \infty$

Gauss' Problem

- Let m denote Lebesgue measure and define

$$m_n(x) = m(G^{-n}[0, x])$$

- In an 1812 letter to Laplace, Gauss stated that he had shown that
- $m_n(x) \rightarrow \frac{\ln(1+x)}{\ln 2}$ as $n \rightarrow \infty$
- and that it would be very desirable to have a good estimate for the error term

Gauss' Problem

- Let m denote Lebesgue measure and define

$$m_n(x) = m(G^{-n}[0, x])$$

- In an 1812 letter to Laplace, Gauss stated that he had shown that
- $m_n(x) \rightarrow \frac{\ln(1+x)}{\ln 2}$ as $n \rightarrow \infty$
- and that it would be very desirable to have a good estimate for the error term

Gauss' Problem

- Let m denote Lebesgue measure and define

$$m_n(x) = m(G^{-n}[0, x])$$

- In an 1812 letter to Laplace, Gauss stated that he had shown that
- $m_n(x) \rightarrow \frac{\ln(1+x)}{\ln 2}$ as $n \rightarrow \infty$
- and that it would be very desirable to have a good estimate for the error term

$$e_n(x) := \left| m_n(x) - \frac{\ln(1+x)}{\ln 2} \right|$$

for large n .

Solution of Gauss' Problem

Solution of Gauss' Problem

- A proof of Gauss' claim didn't surface until 1928 by Kuzmin.

Solution of Gauss' Problem

- A proof of Gauss' claim didn't surface until 1928 by Kuzmin.
- In 1974 Wirsing obtained the optimal bound for the error term $e_n(x)$.

Solution of Gauss' Problem

- A proof of Gauss' claim didn't surface until 1928 by Kuzmin.
- In 1974 Wirsing obtained the optimal bound for the error term $e_n(x)$.
- (Wirsing 74) There is an optimal constant $q \sim .303$ such that $e_n(x) \leq q^n$.

Solution of Gauss' Problem

- A proof of Gauss' claim didn't surface until 1928 by Kuzmin.
- In 1974 Wirsing obtained the optimal bound for the error term $e_n(x)$.
- (Wirsing 74) There is an optimal constant $q \sim .303$ such that $e_n(x) \leq q^n$.
- Why would Gauss say a good estimate would be "very desirable"?

One possibility...

One possibility...

Fix $k, n \in \mathbb{Z}^+$.

One possibility...

Fix $k, n \in \mathbb{Z}^+$.

- What is the probability that a given number $\alpha = [a_1, a_2, \dots]$ has $a_n = k$?

One possibility...

Fix $k, n \in \mathbb{Z}^+$.

- What is the probability that a given number $\alpha = [a_1, a_2, \dots]$ has $a_n = k$?
- The solution to Gauss' Problem provides an excellent estimate for large n .

One possibility...

Fix $k, n \in \mathbb{Z}^+$.

- What is the probability that a given number $\alpha = [a_1, a_2, \dots]$ has $a_n = k$?
- The solution to Gauss' Problem provides an excellent estimate for large n .
- Indeed, say $k = 2$ then

One possibility...

Fix $k, n \in \mathbb{Z}^+$.

- What is the probability that a given number $\alpha = [a_1, a_2, \dots]$ has $a_n = k$?
- The solution to Gauss' Problem provides an excellent estimate for large n .
- Indeed, say $k = 2$ then
- $m\{[a_1, a_2, \dots] : a_n = 2\} = m(G^{-n}[\frac{1}{3}, \frac{1}{2}]) =$

One possibility...

Fix $k, n \in \mathbb{Z}^+$.

- What is the probability that a given number $\alpha = [a_1, a_2, \dots]$ has $a_n = k$?
- The solution to Gauss' Problem provides an excellent estimate for large n .
- Indeed, say $k = 2$ then
- $m\{[a_1, a_2, \dots] : a_n = 2\} = m(G^{-n}[\frac{1}{3}, \frac{1}{2}]) =$
 $= m_n(\frac{1}{2}) - m_n(\frac{1}{3}) \sim \frac{\ln(9/8)}{\ln 2} + (.303\dots)^n.$

The point

The point

- A study of the dynamics of the classical Gauss map has had many applications throughout mathematics (especially probability).

The point

- A study of the dynamics of the classical Gauss map has had many applications throughout mathematics (especially probability).
- One example is the solution of Gauss' problem.

The point

- A study of the dynamics of the classical Gauss map has had many applications throughout mathematics (especially probability).
- One example is the solution of Gauss' problem.
- See "Metrical Theory of Continued Fractions" by Iosifescu & Kraaikamp for complete list.

The point

- A study of the dynamics of the classical Gauss map has had many applications throughout mathematics (especially probability).
- One example is the solution of Gauss' problem.
- See "Metrical Theory of Continued Fractions" by Iosifescu & Kraaikamp for complete list.
- We would like to import these ideas into the noncommutative world.

The point

- A study of the dynamics of the classical Gauss map has had many applications throughout mathematics (especially probability).
- One example is the solution of Gauss' problem.
- See "Metrical Theory of Continued Fractions" by Iosifescu & Kraaikamp for complete list.
- We would like to import these ideas into the noncommutative world.
- Step 1 in this program is importing the Gauss Map to the noncommutative world.

The point

- A study of the dynamics of the classical Gauss map has had many applications throughout mathematics (especially probability).
- One example is the solution of Gauss' problem.
- See "Metrical Theory of Continued Fractions" by Iosifescu & Kraaikamp for complete list.
- We would like to import these ideas into the noncommutative world.
- Step 1 in this program is importing the Gauss Map to the noncommutative world.
- We recall candidates for "noncommutative irrational numbers"

The point

- A study of the dynamics of the classical Gauss map has had many applications throughout mathematics (especially probability).
- One example is the solution of Gauss' problem.
- See "Metrical Theory of Continued Fractions" by Iosifescu & Kraaikamp for complete list.
- We would like to import these ideas into the noncommutative world.
- Step 1 in this program is importing the Gauss Map to the noncommutative world.
- We recall candidates for "noncommutative irrational numbers"
- And for the "noncommutative unit interval."

Effros Shen Algebras

Effros Shen Algebras

- Effros and Shen[80] constructed for each irrational number θ an AF algebra \mathcal{C}_θ .

Effros Shen Algebras

- Effros and Shen[80] constructed for each irrational number θ an AF algebra \mathcal{C}_θ .
- Let $\theta = [a_1, a_2, \dots] = \lim_{n \rightarrow \infty} \frac{p_n}{q_n}$.

Effros Shen Algebras

- Effros and Shen[80] constructed for each irrational number θ an AF algebra \mathcal{C}_θ .
- Let $\theta = [a_1, a_2, \dots] = \lim_{n \rightarrow \infty} \frac{p_n}{q_n}$.
- Then define

$$\mathcal{C}_\theta := \lim_{n \rightarrow \infty} \left(M_{q_n} \oplus M_{q_{n-1}}, \begin{bmatrix} a_n & 1 \\ 1 & 0 \end{bmatrix} \right)$$

Effros Shen Algebras

- Effros and Shen[80] constructed for each irrational number θ an AF algebra \mathcal{C}_θ .
- Let $\theta = [a_1, a_2, \dots] = \lim_{n \rightarrow \infty} \frac{p_n}{q_n}$.
- Then define

$$\mathcal{C}_\theta := \lim_{n \rightarrow \infty} \left(M_{q_n} \oplus M_{q_{n-1}}, \begin{bmatrix} a_n & 1 \\ 1 & 0 \end{bmatrix} \right)$$

- So, \mathcal{C}_θ is approximated by finite dimensional C*-algebras in the same way that θ is approximated by rational numbers.

Effros Shen Algebras

- Effros and Shen[80] constructed for each irrational number θ an AF algebra \mathcal{C}_θ .
- Let $\theta = [a_1, a_2, \dots] = \lim_{n \rightarrow \infty} \frac{p_n}{q_n}$.
- Then define

$$\mathcal{C}_\theta := \lim_{n \rightarrow \infty} \left(M_{q_n} \oplus M_{q_{n-1}}, \begin{bmatrix} a_n & 1 \\ 1 & 0 \end{bmatrix} \right)$$

- So, \mathcal{C}_θ is approximated by finite dimensional C*-algebras in the same way that θ is approximated by rational numbers.
- Let's think of \mathcal{C}_θ as a "noncommutative irrational number."

Boca Mundici Algebra

Boca Mundici Algebra

Boca[08] and Mundici[88,08] (separately) considered an AF algebra, denoted by \mathfrak{A} that "contains" all of the noncommutative irrational numbers:

Boca Mundici Algebra

Boca[08] and Mundici[88,08] (separately) considered an AF algebra, denoted by \mathfrak{A} that "contains" all of the noncommutative irrational numbers:

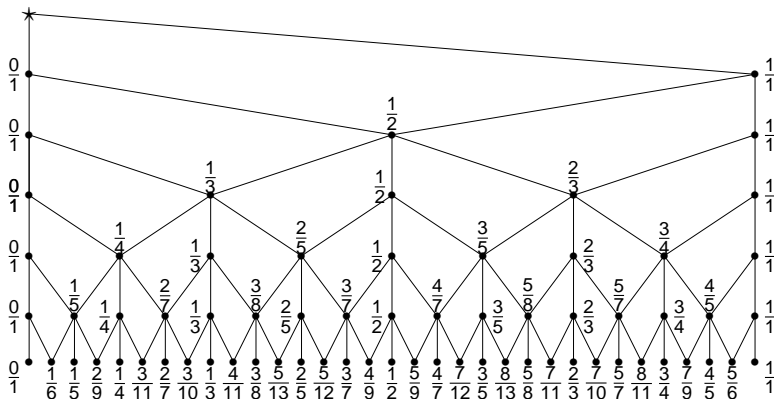


Figure: Bratteli diagram of \mathfrak{A}

Properties of \mathcal{A}

Properties of \mathfrak{A}

- The center of \mathfrak{A} is isomorphic to $C[0, 1]$

Properties of \mathfrak{A}

- The center of \mathfrak{A} is isomorphic to $C[0, 1]$
- The maximal ideal space of \mathfrak{A} is homeomorphic to $[0, 1]$.

Properties of \mathfrak{A}

- The center of \mathfrak{A} is isomorphic to $C[0, 1]$
- The maximal ideal space of \mathfrak{A} is homeomorphic to $[0, 1]$.
- For each $\theta \in [0, 1]$, let I_θ denote the maximal ideal associated to θ

Properties of \mathfrak{A}

- The center of \mathfrak{A} is isomorphic to $C[0, 1]$
- The maximal ideal space of \mathfrak{A} is homeomorphic to $[0, 1]$.
- For each $\theta \in [0, 1]$, let I_θ denote the maximal ideal associated to θ
- For θ irrational $\mathfrak{A}/I_\theta \cong \mathbb{C}$

Properties of \mathfrak{A}

- The center of \mathfrak{A} is isomorphic to $C[0, 1]$
- The maximal ideal space of \mathfrak{A} is homeomorphic to $[0, 1]$.
- For each $\theta \in [0, 1]$, let I_θ denote the maximal ideal associated to θ
- For θ irrational $\mathfrak{A}/I_\theta \cong \mathbb{C}$
- For $\theta = p/q$ we have $\mathfrak{A}/I_\theta \cong M_q$.

Properties of \mathfrak{A}

- The center of \mathfrak{A} is isomorphic to $C[0, 1]$
- The maximal ideal space of \mathfrak{A} is homeomorphic to $[0, 1]$.
- For each $\theta \in [0, 1]$, let I_θ denote the maximal ideal associated to θ
- For θ irrational $\mathfrak{A}/I_\theta \cong \mathcal{C}_\theta$
- For $\theta = p/q$ we have $\mathfrak{A}/I_\theta \cong M_q$.
- So if we (incorrectly) view \mathfrak{A} as operator valued continuous functions on its maximal ideal space..then each function evaluated at θ takes values in the Effros Shen algebra \mathcal{C}_θ .

Properties of \mathfrak{A}

- The center of \mathfrak{A} is isomorphic to $C[0, 1]$
- The maximal ideal space of \mathfrak{A} is homeomorphic to $[0, 1]$.
- For each $\theta \in [0, 1]$, let I_θ denote the maximal ideal associated to θ
- For θ irrational $\mathfrak{A}/I_\theta \cong \mathcal{C}_\theta$
- For $\theta = p/q$ we have $\mathfrak{A}/I_\theta \cong M_q$.
- So if we (incorrectly) view \mathfrak{A} as operator valued continuous functions on its maximal ideal space..then each function evaluated at θ takes values in the Effros Shen algebra \mathcal{C}_θ .
- For these reasons, we feel it is reasonable to attach the moniker "noncommutative unit interval" to \mathfrak{A} .

Definition of G on $C[0, 1]$

Definition of G on $C[0, 1]$

$$G(\alpha) = \begin{cases} 0 & \text{if } \alpha = 0 \\ 1/x - \lfloor 1/x \rfloor & \text{if } \alpha \neq 0 \end{cases}$$

Definition of G on $C[0, 1]$

$$G(\alpha) = \begin{cases} 0 & \text{if } \alpha = 0 \\ 1/x - \lfloor 1/x \rfloor & \text{if } \alpha \neq 0 \end{cases}$$

- Note first that $f \circ G \in C[0, 1] \leftrightarrow f$ is constant.

Definition of G on $C[0, 1]$

$$G(\alpha) = \begin{cases} 0 & \text{if } \alpha = 0 \\ 1/x - \lfloor 1/x \rfloor & \text{if } \alpha \neq 0 \end{cases}$$

- Note first that $f \circ G \in C[0, 1] \leftrightarrow f$ is constant.
- Gauss measure on $[0, 1]$ is defined as $d\mu = \frac{\ln(1+x)}{\ln 2} dx$.

Definition of G on $C[0, 1]$

$$G(\alpha) = \begin{cases} 0 & \text{if } \alpha = 0 \\ 1/x - \lfloor 1/x \rfloor & \text{if } \alpha \neq 0 \end{cases}$$

- Note first that $f \circ G \in C[0, 1] \leftrightarrow f$ is constant.
- Gauss measure on $[0, 1]$ is defined as $d\mu = \frac{\ln(1+x)}{\ln 2} dx$.
- μ is the unique G -invariant probability measure AC w.r.t m .

Definition of G on $C[0, 1]$

$$G(\alpha) = \begin{cases} 0 & \text{if } \alpha = 0 \\ 1/x - \lfloor 1/x \rfloor & \text{if } \alpha \neq 0 \end{cases}$$

- Note first that $f \circ G \in C[0, 1] \leftrightarrow f$ is constant.
- Gauss measure on $[0, 1]$ is defined as $d\mu = \frac{\ln(1+x)}{\ln 2} dx$.
- μ is the unique G -invariant probability measure AC w.r.t m .
- Hence $V_G(f) = f \circ G$ defines an isometry on $L^2([0, 1], \mu)$

Definition of G on $C[0, 1]$

$$G(\alpha) = \begin{cases} 0 & \text{if } \alpha = 0 \\ 1/x - \lfloor 1/x \rfloor & \text{if } \alpha \neq 0 \end{cases}$$

- Note first that $f \circ G \in C[0, 1] \leftrightarrow f$ is constant.
- Gauss measure on $[0, 1]$ is defined as $d\mu = \frac{\ln(1+x)}{\ln 2} dx$.
- μ is the unique G -invariant probability measure AC w.r.t m .
- Hence $V_G(f) = f \circ G$ defines an isometry on $L^2([0, 1], \mu)$
- Conjugation by V_G provides a UCP map on $C[0, 1]$:

Definition of G on $C[0, 1]$

$$G(\alpha) = \begin{cases} 0 & \text{if } \alpha = 0 \\ 1/x - \lfloor 1/x \rfloor & \text{if } \alpha \neq 0 \end{cases}$$

- Note first that $f \circ G \in C[0, 1] \leftrightarrow f$ is constant.
- Gauss measure on $[0, 1]$ is defined as $d\mu = \frac{\ln(1+x)}{\ln 2} dx$.
- μ is the unique G -invariant probability measure AC w.r.t m .
- Hence $V_G(f) = f \circ G$ defines an isometry on $L^2([0, 1], \mu)$
- Conjugation by V_G provides a UCP map on $C[0, 1]$:
- $\mathbb{G}(f)(\theta) = \sum_{s=1}^{\infty} f\left(\frac{1}{\theta+s}\right) \frac{1+\theta}{(\theta+s)(\theta+s+1)}$

Properties of \mathbb{G}

Properties of \mathbb{G}

- π_μ GNS representation of $C[0, 1]$ w.r.t. μ then

Properties of \mathbb{G}

- π_μ GNS representation of $C[0, 1]$ w.r.t. μ then
$$\pi_\mu(\mathbb{G}(f)) = V_G^* \pi_\mu(f) V_G.$$

Properties of \mathbb{G}

- π_μ GNS representation of $C[0, 1]$ w.r.t. μ then
$$\pi_\mu(\mathbb{G}(f)) = V_G^* \pi_\mu(f) V_G.$$
- $\int f d\mu = \int \mathbb{G}(f) d\mu$

Properties of \mathbb{G}

- π_μ GNS representation of $C[0, 1]$ w.r.t. μ then
$$\pi_\mu(\mathbb{G}(f)) = V_G^* \pi_\mu(f) V_G.$$
- $\int f d\mu = \int \mathbb{G}(f) d\mu$
- \mathbb{G} acts on the maximal ideals of $C[0, 1]$ in the same manner that G acts on $[0, 1]$:

Properties of \mathbb{G}

- π_μ GNS representation of $C[0, 1]$ w.r.t. μ then
$$\pi_\mu(\mathbb{G}(f)) = V_G^* \pi_\mu(f) V_G.$$
- $\int f d\mu = \int \mathbb{G}(f) d\mu$
- \mathbb{G} acts on the maximal ideals of $C[0, 1]$ in the same manner that G acts on $[0, 1]$:
Set $I_\theta = \{f \in C[0, 1] : f(\theta) = 0\}$.

Properties of \mathbb{G}

- π_μ GNS representation of $C[0, 1]$ w.r.t. μ then

$$\pi_\mu(\mathbb{G}(f)) = V_G^* \pi_\mu(f) V_G.$$
- $\int f d\mu = \int \mathbb{G}(f) d\mu$
- \mathbb{G} acts on the maximal ideals of $C[0, 1]$ in the same manner that G acts on $[0, 1]$:
 Set $I_\theta = \{f \in C[0, 1] : f(\theta) = 0\}$.
 Set $\theta_s = G^{-1}(\theta) \cap [1/(s+1), 1/s]$

Properties of \mathbb{G}

- π_μ GNS representation of $C[0, 1]$ w.r.t. μ then

$$\pi_\mu(\mathbb{G}(f)) = V_G^* \pi_\mu(f) V_G.$$
- $\int f d\mu = \int \mathbb{G}(f) d\mu$
- \mathbb{G} acts on the maximal ideals of $C[0, 1]$ in the same manner that G acts on $[0, 1]$:
 Set $I_\theta = \{f \in C[0, 1] : f(\theta) = 0\}$.
 Set $\theta_s = G^{-1}(\theta) \cap [1/(s+1), 1/s]$
- Then $\mathbb{G}(I_{\theta_s}) = I_\theta$.

Properties of \mathbb{G}

- π_μ GNS representation of $C[0, 1]$ w.r.t. μ then

$$\pi_\mu(\mathbb{G}(f)) = V_G^* \pi_\mu(f) V_G.$$
- $\int f d\mu = \int \mathbb{G}(f) d\mu$
- \mathbb{G} acts on the maximal ideals of $C[0, 1]$ in the same manner that G acts on $[0, 1]$:
 Set $I_\theta = \{f \in C[0, 1] : f(\theta) = 0\}$.
 Set $\theta_s = G^{-1}(\theta) \cap [1/(s+1), 1/s]$
- Then $\mathbb{G}(I_{\theta_s}) = I_\theta$.
- These are the properties we want our noncommutative extension to inherit.

Gauss Measure on \mathfrak{A}

Gauss Measure on \mathfrak{A}

Theorem (E 09)

Let ν be a state on $C[0, 1]$. Then ν has a unique tracial extension, τ_ν , to \mathfrak{A} .

Gauss Measure on \mathfrak{A}

Theorem (E 09)

Let ν be a state on $C[0, 1]$. Then ν has a unique tracial extension, τ_ν , to \mathfrak{A} .

Gauss Measure on \mathfrak{A}

Theorem (E 09)

Let ν be a state on $C[0, 1]$. Then ν has a unique tracial extension, τ_ν , to \mathfrak{A} .

We let τ_μ be the unique tracial extension of μ to \mathfrak{A} .

Extension to \mathcal{A}

Extension to \mathfrak{A}

- Recall $\mathbb{G}(f)(\theta) = \sum_{s=1}^{\infty} f\left(\frac{1}{\theta+s}\right) \frac{1+\theta}{(\theta+s)(\theta+s+1)}$ for $f \in C[0, 1]$.

Extension to \mathfrak{A}

- Recall $\mathbb{G}(f)(\theta) = \sum_{s=1}^{\infty} f\left(\frac{1}{\theta+s}\right) \frac{1+\theta}{(\theta+s)(\theta+s+1)}$ for $f \in C[0, 1]$.
- Since $\frac{1+\theta}{(\theta+s)(\theta+s+1)} \in C[0, 1] \subseteq \mathfrak{A}$,

Extension to \mathfrak{A}

- Recall $\mathbb{G}(f)(\theta) = \sum_{s=1}^{\infty} f\left(\frac{1}{\theta+s}\right) \frac{1+\theta}{(\theta+s)(\theta+s+1)}$ for $f \in C[0, 1]$.
- Since $\frac{1+\theta}{(\theta+s)(\theta+s+1)} \in C[0, 1] \subseteq \mathfrak{A}$,
- We only have to consider extending the action $f \mapsto f \circ g_s$ for each $s \in \mathbb{N}$

Extension to \mathfrak{A}

- Recall $\mathbb{G}(f)(\theta) = \sum_{s=1}^{\infty} f\left(\frac{1}{\theta+s}\right) \frac{1+\theta}{(\theta+s)(\theta+s+1)}$ for $f \in C[0, 1]$.
- Since $\frac{1+\theta}{(\theta+s)(\theta+s+1)} \in C[0, 1] \subseteq \mathfrak{A}$,
- We only have to consider extending the action $f \mapsto f \circ g_s$ for each $s \in \mathbb{N}$
- where $g_s(\theta) = \frac{1}{\theta+s}$.

Extension to \mathfrak{A}

- Recall $\mathbb{G}(f)(\theta) = \sum_{s=1}^{\infty} f\left(\frac{1}{\theta+s}\right) \frac{1+\theta}{(\theta+s)(\theta+s+1)}$ for $f \in C[0, 1]$.
- Since $\frac{1+\theta}{(\theta+s)(\theta+s+1)} \in C[0, 1] \subseteq \mathfrak{A}$,
- We only have to consider extending the action $f \mapsto f \circ g_s$ for each $s \in \mathbb{N}$
- where $g_s(\theta) = \frac{1}{\theta+s}$.
- Let's outline this extension for $s = 1$.

Extension of Composition of g_1

Extension of Composition of g_1

The map $g_1 : [0, 1] \rightarrow [\frac{1}{2}, 1]$ shrinks $[0, 1]$ in half and then flips it.

Extension of Composition of g_1

The map $g_1 : [0, 1] \rightarrow [\frac{1}{2}, 1]$ shrinks $[0, 1]$ in half and then flips it.
We want to imitate this on the Bratelli diagram of \mathfrak{A} :

Extension of Composition of g_1

The map $g_1 : [0, 1] \rightarrow [\frac{1}{2}, 1]$ shrinks $[0, 1]$ in half and then flips it. We want to imitate this on the Bratelli diagram of \mathfrak{A} :

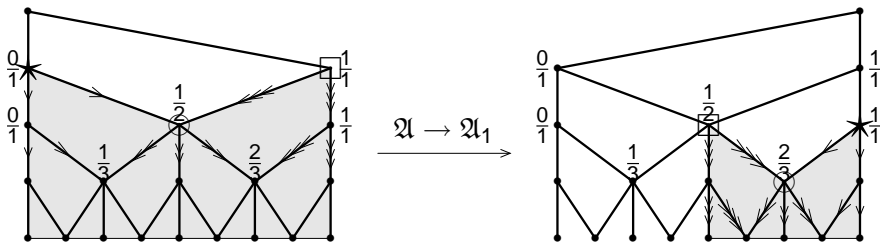


Figure: Bratelli Diagram of \mathfrak{A}Bratelli Diagram of Quotient of \mathfrak{A}

The Problem

The Problem

- For example, we want to map the "node" $\frac{1}{2}$ to the node $\frac{2}{3}$.

The Problem

- For example, we want to map the "node" $\frac{1}{2}$ to the node $\frac{2}{3}$.
- We *want* a map $T : M_2 \rightarrow M_3$ such that

The Problem

- For example, we want to map the "node" $\frac{1}{2}$ to the node $\frac{2}{3}$.
- We *want* a map $T : M_2 \rightarrow M_3$ such that
 1. T is unital completely positive.

The Problem

- For example, we want to map the "node" $\frac{1}{2}$ to the node $\frac{2}{3}$.
- We *want* a map $T : M_2 \rightarrow M_3$ such that
 1. T is unital completely positive.
 2. The induced map $T : L^2(M_2, \tau_2) \rightarrow L^2(M_3, \tau_3)$ is an isometry.

The Problem

- For example, we want to map the "node" $\frac{1}{2}$ to the node $\frac{2}{3}$.
- We want a map $T : M_2 \rightarrow M_3$ such that
 1. T is unital completely positive.
 2. The induced map $T : L^2(M_2, \tau_2) \rightarrow L^2(M_3, \tau_3)$ is an isometry.
- Since $2 \nmid 3$, we can't simultaneously satisfy 1 and 2.

The Problem

- For example, we want to map the "node" $\frac{1}{2}$ to the node $\frac{2}{3}$.
- We *want* a map $T : M_2 \rightarrow M_3$ such that
 1. T is unital completely positive.
 2. The induced map $T : L^2(M_2, \tau_2) \rightarrow L^2(M_3, \tau_3)$ is an isometry.
- Since $2 \nmid 3$, we can't simultaneously satisfy 1 and 2.
- For this reason, we define a CP map that preserves as much trace as possible with induced map an L^2 -isometry..

Fixing the Problem

Fixing the Problem

Define the CP map $T : M_2 \rightarrow M_3$ as

$$T(x) = \begin{bmatrix} x & 0 \\ 0 & 0 \end{bmatrix} \quad \& \quad \phi_3 = (3/2)\tau_3 \circ T.$$

Fixing the Problem

Define the CP map $T : M_2 \rightarrow M_3$ as

$$T(x) = \begin{bmatrix} x & 0 \\ 0 & 0 \end{bmatrix} \quad \& \quad \phi_3 = (3/2)\tau_3 \circ T.$$

- Induced map $T : L^2(M_2, \tau_2) \rightarrow L^2(M_3, \phi_3)$ is isometry.

Fixing the Problem

Define the CP map $T : M_2 \rightarrow M_3$ as

$$T(x) = \begin{bmatrix} x & 0 \\ 0 & 0 \end{bmatrix} \quad \& \quad \phi_3 = (3/2)\tau_3 \circ T.$$

- Induced map $T : L^2(M_2, \tau_2) \rightarrow L^2(M_3, \phi_3)$ is isometry.
- The induced adjoint map T^* is UCP from $M_3 \rightarrow M_2$.

Fixing the Problem

Define the CP map $T : M_2 \rightarrow M_3$ as

$$T(x) = \begin{bmatrix} x & 0 \\ 0 & 0 \end{bmatrix} \quad \& \quad \phi_3 = (3/2)\tau_3 \circ T.$$

- Induced map $T : L^2(M_2, \tau_2) \rightarrow L^2(M_3, \phi_3)$ is isometry.
- The induced adjoint map T^* is UCP from $M_3 \rightarrow M_2$.
- Using the adjoint maps T^* , we build a big commutative diagram (that preserves all the stuff we want to preserve),

Fixing the Problem

Define the CP map $T : M_2 \rightarrow M_3$ as

$$T(x) = \begin{bmatrix} x & 0 \\ 0 & 0 \end{bmatrix} \quad \& \quad \phi_3 = (3/2)\tau_3 \circ T.$$

- Induced map $T : L^2(M_2, \tau_2) \rightarrow L^2(M_3, \phi_3)$ is isometry.
- The induced adjoint map T^* is UCP from $M_3 \rightarrow M_2$.
- Using the adjoint maps T^* , we build a big commutative diagram (that preserves all the stuff we want to preserve),
- take a limit to obtain a UCP map $G_1 : \mathfrak{A}_1 \rightarrow \mathfrak{A}$.

Fixing the Problem

Define the CP map $T : M_2 \rightarrow M_3$ as

$$T(x) = \begin{bmatrix} x & 0 \\ 0 & 0 \end{bmatrix} \quad \& \quad \phi_3 = (3/2)\tau_3 \circ T.$$

- Induced map $T : L^2(M_2, \tau_2) \rightarrow L^2(M_3, \phi_3)$ is isometry.
- The induced adjoint map T^* is UCP from $M_3 \rightarrow M_2$.
- Using the adjoint maps T^* , we build a big commutative diagram (that preserves all the stuff we want to preserve),
- take a limit to obtain a UCP map $G_1 : \mathfrak{A}_1 \rightarrow \mathfrak{A}$.
- Let $\tilde{G}_1 = G_1 \circ \pi_1$.

Fixing the Problem

Define the CP map $T : M_2 \rightarrow M_3$ as

$$T(x) = \begin{bmatrix} x & 0 \\ 0 & 0 \end{bmatrix} \quad \& \quad \phi_3 = (3/2)\tau_3 \circ T.$$

- Induced map $T : L^2(M_2, \tau_2) \rightarrow L^2(M_3, \phi_3)$ is isometry.
- The induced adjoint map T^* is UCP from $M_3 \rightarrow M_2$.
- Using the adjoint maps T^* , we build a big commutative diagram (that preserves all the stuff we want to preserve),
- take a limit to obtain a UCP map $G_1 : \mathfrak{A}_1 \rightarrow \mathfrak{A}$.
- Let $\tilde{G}_1 = G_1 \circ \pi_1$.

Fixing the Problem

Define the CP map $T : M_2 \rightarrow M_3$ as

$$T(x) = \begin{bmatrix} x & 0 \\ 0 & 0 \end{bmatrix} \quad \& \quad \phi_3 = (3/2)\tau_3 \circ T.$$

- Induced map $T : L^2(M_2, \tau_2) \rightarrow L^2(M_3, \phi_3)$ is isometry.
- The induced adjoint map T^* is UCP from $M_3 \rightarrow M_2$.
- Using the adjoint maps T^* , we build a big commutative diagram (that preserves all the stuff we want to preserve),
- take a limit to obtain a UCP map $G_1 : \mathfrak{A}_1 \rightarrow \mathfrak{A}$.
- Let $\tilde{G}_1 = G_1 \circ \pi_1$. Define \tilde{G}_2, \dots similarly. Then,

Fixing the Problem

Define the CP map $T : M_2 \rightarrow M_3$ as

$$T(x) = \begin{bmatrix} x & 0 \\ 0 & 0 \end{bmatrix} \quad \& \quad \phi_3 = (3/2)\tau_3 \circ T.$$

- Induced map $T : L^2(M_2, \tau_2) \rightarrow L^2(M_3, \phi_3)$ is isometry.
- The induced adjoint map T^* is UCP from $M_3 \rightarrow M_2$.
- Using the adjoint maps T^* , we build a big commutative diagram (that preserves all the stuff we want to preserve),
- take a limit to obtain a UCP map $G_1 : \mathfrak{A}_1 \rightarrow \mathfrak{A}$.
- Let $\tilde{G}_1 = G_1 \circ \pi_1$. Define \tilde{G}_2, \dots similarly. Then,

$$\tilde{G} = \sum_{s=1}^{\infty} \tilde{G}_s \frac{1 + \theta}{(\theta + s)(\theta + s + 1)}.$$

Extension Theorem

Extension Theorem

Theorem (E 09)

There exist

Extension Theorem

Theorem (E 09)

There exist

- i. A UCP map $\tilde{G} : \mathfrak{A} \rightarrow \mathfrak{A}$

Extension Theorem

Theorem (E 09)

There exist

- i. A UCP map $\tilde{G} : \mathfrak{A} \rightarrow \mathfrak{A}$
- ii. State and tracial extensions ϕ, τ_μ of Gauss measure μ

Extension Theorem

Theorem (E 09)

There exist

- i. A UCP map $\tilde{G} : \mathfrak{A} \rightarrow \mathfrak{A}$
- ii. State and tracial extensions ϕ, τ_μ of Gauss measure μ
- iii. An isometry $\tilde{V}_G : L^2(\mathfrak{A}, \tau) \rightarrow L^2(\mathfrak{A}, \phi)$ such that

Extension Theorem

Theorem (E 09)

There exist

- i. A UCP map $\tilde{\mathbb{G}} : \mathfrak{A} \rightarrow \mathfrak{A}$
- ii. State and tracial extensions ϕ, τ_μ of Gauss measure μ
- iii. An isometry $\tilde{V}_G : L^2(\mathfrak{A}, \tau) \rightarrow L^2(\mathfrak{A}, \phi)$ such that
 1. $\tilde{\mathbb{G}}|_{C[0,1]} = \mathbb{G}$.

Extension Theorem

Theorem (E 09)

There exist

- i. A UCP map $\tilde{\mathbb{G}} : \mathfrak{A} \rightarrow \mathfrak{A}$
- ii. State and tracial extensions ϕ, τ_μ of Gauss measure μ
- iii. An isometry $\tilde{V}_G : L^2(\mathfrak{A}, \tau) \rightarrow L^2(\mathfrak{A}, \phi)$ such that
 1. $\tilde{\mathbb{G}}|_{C[0,1]} = \mathbb{G}$.
 2. $\tilde{\mathbb{G}}(\mathcal{J}(\theta_s)) = \mathcal{J}(\theta)$.

Extension Theorem

Theorem (E 09)

There exist

- i. A UCP map $\tilde{\mathbb{G}} : \mathfrak{A} \rightarrow \mathfrak{A}$
- ii. State and tracial extensions ϕ, τ_μ of Gauss measure μ
- iii. An isometry $\tilde{V}_G : L^2(\mathfrak{A}, \tau) \rightarrow L^2(\mathfrak{A}, \phi)$ such that
 1. $\tilde{\mathbb{G}}|_{C[0,1]} = \mathbb{G}$.
 2. $\tilde{\mathbb{G}}(\mathcal{J}(\theta_s)) = \mathcal{J}(\theta)$.
 3. $\tilde{V}_G|_{L^2([0,1],\mu)} = V_G$ and $\tilde{V}_G^*|_{L^2([0,1],\mu)} = V_G^*$.

Extension Theorem

Theorem (E 09)

There exist

- i. A UCP map $\tilde{\mathbb{G}} : \mathfrak{A} \rightarrow \mathfrak{A}$
- ii. State and tracial extensions ϕ, τ_μ of Gauss measure μ
- iii. An isometry $\tilde{V}_G : L^2(\mathfrak{A}, \tau) \rightarrow L^2(\mathfrak{A}, \phi)$ such that
 1. $\tilde{\mathbb{G}}|_{C[0,1]} = \mathbb{G}$.
 2. $\tilde{\mathbb{G}}(\mathcal{J}(\theta_s)) = \mathcal{J}(\theta)$.
 3. $\tilde{V}_G|_{L^2([0,1],\mu)} = V_G$ and $\tilde{V}_G^*|_{L^2([0,1],\mu)} = V_G^*$.
 4. $\tilde{V}_G^* \pi_\phi(x) \tilde{V}_G = \pi_{\tau_\mu}(\tilde{\mathbb{G}}(x))$ for $x \in \mathfrak{A}$.

Extension Theorem

Theorem (E 09)

There exist

- i. A UCP map $\tilde{\mathbb{G}} : \mathfrak{A} \rightarrow \mathfrak{A}$
- ii. State and tracial extensions ϕ, τ_μ of Gauss measure μ
- iii. An isometry $\tilde{V}_G : L^2(\mathfrak{A}, \tau) \rightarrow L^2(\mathfrak{A}, \phi)$ such that
 1. $\tilde{\mathbb{G}}|_{C[0,1]} = \mathbb{G}$.
 2. $\tilde{\mathbb{G}}(\mathcal{J}(\theta_s)) = \mathcal{J}(\theta)$.
 3. $\tilde{V}_G|_{L^2([0,1],\mu)} = V_G$ and $\tilde{V}_G^*|_{L^2([0,1],\mu)} = V_G^*$.
 4. $\tilde{V}_G^* \pi_\phi(\mathbf{x}) \tilde{V}_G = \pi_{\tau_\mu}(\tilde{\mathbb{G}}(\mathbf{x}))$ for $\mathbf{x} \in \mathfrak{A}$.
 5. $\phi(\mathbf{x}) = \tau_\mu(\tilde{\mathbb{G}}(\mathbf{x}))$ for $\mathbf{x} \in \mathfrak{A}$.

Mange tak!